Disentangled Fair Representations

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Fairness Through Adversarial Learning

• Adversarial Learning

 $L(f,g,h,k) = \alpha L_C(g(f(X,A)),Y) + \beta L_{Dec}(k(f(X,A),A),X) + \gamma L_{Adv}(h(f(X,A)),A)) + \beta L_{Dec}(k(f(X,A),A),X) + \beta L_{Adv}(h(f(X,A)),A)) + \beta L_{Dec}(k(f(X,A),A),X) + \beta L_{Adv}(h(f(X,A)),A)) + \beta L_{Dec}(k(f(X,A),A),X) + \beta L_{Adv}(h(f(X,A)),A)) + \beta L_{Adv}(h(f(X,A)),A)) + \beta L_{Adv}(h(f(X,A)),A) + \beta L_{Adv}(h(f(X,A)),A) + \beta L_{Adv}(h(f(X,A)),A)) + \beta L_{Adv}(h(f(X,A)),A) + \beta L_{Adv}(h(f(X,A)$



Madras et al, 2018

Transfer Fair Representations

Heritage Health Dataset

- Comprises insurance claims and physician records
- Task 1 Predict Charlson index (prediction of 10 year survival of patients) trained using equalized odds adversarial objective
- Task 2 Same input, task becomes predicting a patient's insurance claim corresponding to a specific medical condition

Transfer- unf - MLP with no fairness constraints Transfer- fair - MLP with fairness constraints in <u>Bechavod et al, 2017</u> Transfer - Y - Adv baseline in <u>Zhang et al, 2018</u>



Madras et al, 2018

Outline

- Disentangled Representations
- Flexibly Fair Representation
- Orthogonal Disentangled Fair Representations
- Measurements for Disentangled Fair Representations

VAE Revisited



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Ζ

VAE Revisited



 $L_{\text{VAE}}(p,q) = \mathbb{E}_{q(z|x)} \left[\log p(x|z) \right] - D_{KL} \left[q(z|x) || p(z) \right]$

Disentanglement in VAE

$$L_{\text{VAE}}(p,q) = \mathbb{E}_{q(z|x)} \left[\log p(x|z) \right] - D_{KL} \left[q(z|x) || p(z) \right]$$



Higgins et al, 2017

β-VAE

$L_{\beta \text{VAE}}(p,q) = \mathbb{E}_{q(z|x)} \left[\log p(x|z) \right] - \beta D_{KL} \left[q(z|x) || p(z) \right]$ $\beta = 1$

							•	•	orig	
				-			•		recon	
٠	٠	•	•	•					KL = 3.39 $\sigma = 0.08$	
٠	٠	•	٠					2	KL = 2.57 $\sigma = 0.20$	
٠	٠	•		•	•	٠			KL = 2.32 $\sigma = 0.20$	
		•		٠	•				KL = 1.43 $\sigma = 0.43$	
•		•					•	٠	KL = 0.00 $\sigma = 1.01$	
•									$\sigma = 0.00$	

 $\beta = 150$



FactorVAE

$$L_{\text{FactorVAE}}(p,q) = \mathbb{E}_{q(z|x)} \left[\log p(x|z) \right]$$
$$- D_{KL} \left[q(z|x) || p(z) \right]$$
$$- \gamma D_{KL}(q(z)) || \prod_{j} q(z_{j}))$$

 z_i correlates with z_j if and only if i = j

Kim et al, 2018

β-VAE and FactorVAE β -VAE



Models find x-position, y-position, and scale, but struggle to disentangle orientation and shape

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x

Training



Creager et al, 2019

Disentangled Fair Representations

$$q(z,b) = q(z) \prod_j q(b_j)$$

- Demographic Parity for Feature a,
 - Ignoring a_i use instead [z, b]\b_i
 - o or replace b, with independent noise
- Compositional Procedure
- z non-sensitive dimension of the latent variables
- b sensitive dimensions of the latent variables

Creager et al, 2019

- $z \perp b_j \forall j$ (disentanglement of the non-sensitive and sensitive latent dimensions);
- $b_i \perp b_j \forall i \neq j$ (disentanglement of the various different sensitive dimensions);
- MI(a_j, b_j) is large ∀ j (predictiveness of each sensitive dimension);

$$\begin{split} L_{\text{FFVAE}}(p,q) &= \mathbb{E}_{q(z,b|x,a)} \left[\log p(x,a|z,b) \right] \\ \begin{array}{c} z \perp b_{j} \\ p(z,b) = p(z)p(b) \\ \text{Standard Uniform} \\ b_{i} \perp b_{j} \forall i \neq j \end{array} \begin{array}{c} -D_{KL} \left[q(z,b|x) || p(z,b) \right] \\ \hline \beta \text{-VAE} \\ -\gamma D_{KL} (q(z,b)) || q(z) \prod_{j} q(b_{j})) \\ j \\ \hline \text{factor-VAE} \\ \end{split}$$

$$\mathbb{E}_{q(z,b|x,a)} \left[\log p(x,a|z,b)
ight] \longrightarrow \mathbb{E}_{q(z,b|x)} \left[\log p(x|z,b) + lpha \log p(a|b)
ight] \ _{p(x,a|z,b) = p(x|z,b)p(a|b)}$$

$$\begin{split} L_{\text{FFVAE}}(p,q) &= \mathbb{E}_{q(z,b|x)}[\log p(x|z,b) + \alpha \log p(a|b)] \\ &- \gamma D_{KL}(q(z,b)||q(z)\prod_{j}q(b_{j})) \\ &- D_{KL}\left[q(z,b|x)||p(z,b)\right]. \end{split}$$

Experiments

- Fair Classification
 - Make fair predictions
- Predictiveness
 - Train a classifier to predict sensitive attribute a_i from b_i alone
- Disentanglement
 - Train a classifier to predict sensitive attribute a_i from representations with b_i removed



Communities & Crime

Fair Classification

$$\Delta_{DP}(g) \triangleq d_g(\mathcal{Z}_0, \mathcal{Z}_1) = |\mathbb{E}_{\mathcal{Z}_0}[g] - \mathbb{E}_{\mathcal{Z}_1}[g]|$$
$$\Delta_{DP}(g) = 0 \quad \longleftrightarrow \quad g(Z) \perp A$$

- Sensitive attributes:
 - racePctBlack (R)
 - blackPerCapIncome (B)
 - pctNotSpeakEnglWell (P)
- y = violentCrimesPerCaptia



CelebA

Fair Classification



0.725

¥ 0.700

0.675

0.650

0.625 0.00 0.05 0.10 0.15 0.20 0.25 0.30 0.35 0.40 Δ_{CPP}

(m) $a = E \land \neg M$

0.700·

0.675

0.650

0.625

0.05 0.10 0.15 0.20 0.25 0.30 0.35 0.40 Δpp

(n) $a = \neg E \land M$

0.725

0.700

0.675

0.650

0.625 0.00 0.05 0.10 0.15 0.20 0.25 0.30 0.35 0.40

(o) $a = \neg E \land \neg M$

- Chubby (C) Ο
- Eyeglasses (E) Ο
- Male (M) Ο
- y = HeavyMakeup.

DSpritesUnfair Dataset

Fair Classification

2D shapes procedurally generated from 6 ground truth independent latent factors. These factors are color, shape, scale, rotation, x and y positions of a sprite.





DSpritesUnfair Dataset

- Disentanglement Predict sensitive attribute a_i from b_i alone
- Predictiveness Predict sensitive attribute a_i from representations with b_i removed



$$\mathbb{E}_{\text{FFVAE}}(p,q) = \mathbb{E}_{q(z,b|x)} [\log p(x|z,b) + \alpha \log p(a|b)] \\ - \gamma D_{KL}(q(z,b)||q(z) \prod_{j} q(b_{j})) \\ - D_{KL} [q(z,b|x)||p(z,b)].$$

Comparisons to Adversarial Learning



Adversarial Learning

Outline

- Disentangled Representations
- Flexibly Fair Representation
- Orthogonal Disentangled Fair Representations
- Measurements for Disentangled Fair Representations

Orthogonal Disentangled Fair Representations

- Train a fair representation that is
 - Disentangled
 - and Orthogonal



 $\arg\min_{\theta_T,\theta_S,\phi_T,\phi_S} \underline{\mathcal{L}_T(\theta_T,\phi_T)} + \underline{\mathcal{L}_S(\theta_S^*,\phi_S)} + \lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_{OD}(\theta_T,\theta_S)$

$$\mathcal{L}_{T}(\theta_{T}, \phi_{T}) = \mathrm{KL}(p(\boldsymbol{y}|\boldsymbol{x}) \mid\mid q_{\phi_{T}}(\boldsymbol{y}|\boldsymbol{z_{T}}))$$
$$\mathcal{L}_{S}(\theta_{S}^{*}, \phi_{S}) = \mathrm{KL}(p(\boldsymbol{s}|\boldsymbol{x}) \mid\mid q_{\phi_{S}}(\boldsymbol{s}|\boldsymbol{z_{S}}))$$

Matching the probabilities of ground truth (i.e., y) and sensitive information (i.e., s).

 $\arg\min_{\theta_T,\theta_S,\phi_T,\phi_S} \mathcal{L}_T(\theta_T,\phi_T) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_{OD}(\theta_T,\theta_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_{OD}(\theta_T,\theta_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_{OD}(\theta_T,\theta_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_{OD}(\theta_T,\theta_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_{OD}(\theta_T,\theta_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_{OD}(\theta_T,\theta_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_{OD}(\theta_T,\theta_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_{OD}(\theta_T,\theta_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_{OD}(\theta_T,\theta_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_{OD}(\theta_T,\theta_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_S(\theta_S^*,\phi_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_S(\theta_S^*,\phi_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_S) + \lambda_{OD} \mathcal{L}_S(\theta_S^*,\phi_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_E(\phi_S,\theta_S) + \lambda_E \mathcal{L}_S(\theta_S^*,\phi_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_S(\theta_S^*,\phi_S) + \lambda_E \mathcal{L}_S(\theta_S^*,\phi_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_S(\theta_S^*,\phi_S) + \lambda_E \mathcal{L}_S(\theta_S^*,\phi_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \mathcal{L}_S(\theta_S^*,\phi_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_S(\theta_S^*,\phi_S) + \lambda_E \mathcal{L}_S(\theta_S^*,\phi_S) + \lambda_E \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_S(\theta_S^*,\phi_S) + \lambda_E \mathcal{L}_S(\theta_S^*,\phi_S)}_{+ \mathcal{L}_S(\theta_S^*,\phi_S) + \underbrace{\lambda_E \mathcal{L}_S(\theta_S^*,\phi_S) + \lambda_E \mathcal{L}_S(\theta_S^*,\phi_S) + \lambda_E \mathcal{L}_S(\theta_S^*,\phi_S) +$

$\mathcal{L}_E(\phi_S, \theta_T) = \mathrm{KL}(q_{\phi_S}(\boldsymbol{s}|\boldsymbol{z_T}) || \mathcal{U}(\boldsymbol{s}))$

Makes sure that none sensitive information got leaked into the prediction z_{τ}

 $\arg\min_{\theta_T,\theta_S,\phi_T,\phi_S} \mathcal{L}_T(\theta_T,\phi_T) + \mathcal{L}_S(\theta_S^*,\phi_S) + \lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \underbrace{\lambda_{OD} \mathcal{L}_{OD}(\theta_T,\theta_S)}_{}$

$$\mathcal{L}_{OD}(\theta_T, \theta_S) = \mathcal{L}_{\boldsymbol{z_T}}(\theta_T) + \mathcal{L}_{\boldsymbol{z_S}}(\theta_S)$$

$$\mathcal{L}_{\boldsymbol{z_T}}(\theta_T) = \mathrm{KL}(q_{\theta_T}(\boldsymbol{z_T}|\boldsymbol{x}) || p(\boldsymbol{z_T}))$$
$$p(\boldsymbol{z_S}) = \mathcal{N}([0,1]^T, I) \quad p(\boldsymbol{z_T}) = \mathcal{N}([1,0]^T, I)$$

Enforces both Disentanglement and Orthogonality



 $\arg\min_{\theta_T,\theta_S,\phi_T,\phi_S} \mathcal{L}_T(\theta_T,\phi_T) + \mathcal{L}_S(\theta_S^*,\phi_S) + \lambda_E \mathcal{L}_E(\phi_S,\theta_T) + \lambda_{OD} \mathcal{L}_{OD}(\theta_T,\theta_S)$

Adult, German, and extended YaleB





(a) Target attribute classification accuracy.



(b) Sensitive attribute classification accuracy.

Visualizations on the Embeddings



YaleB faces

CIFAR 10

Comparisons to Flexibly Fair Representation

- How do they handle leakage of sensitive information to the representations?
- How do they handle disentanglement?





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Measurements for Disentangled Fair Representations



Locatello et al, 2019

Unfairness Measure

- Measuring Unfairness Without Ground Truth
 - Total Variation (TV) of prediction pairs across groups

$$\texttt{unfairness}(\hat{\mathbf{y}}) = \frac{1}{|S|} \sum_{s} TV(p(\hat{\mathbf{y}}), p(\hat{\mathbf{y}} \mid \mathbf{s} = s)) \; \forall \; y$$

Results Using Models Trained in Locatello et al, 2019



A - dSprites, B - Color-dSprites, C - Noisy-dSprites D - Scream-dSprites, E - SmallNORB, F - Cars3D, G - Shapes3D

Locatello et al, 2019

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Reading Assignments (Disentangled Fair Representations)

- Zhao, Han, Amanda Coston, Tameem Adel, and Geoffrey J. Gordon. Conditional learning of fair representations, ICLR 2020
- Zhao, Han, and Geoff Gordon. Inherent tradeoffs in learning fair representations, NeurIPS 2019
- He, Yuzi, Keith Burghardt, and Kristina Lerman. A Geometric Solution to Fair Representations, AAAI/ACM AI, Ethics, and Society 2020
- Ruoss, Anian, Mislav Balunović, Marc Fischer, and Martin Vechev. Learning Certified Individually Fair Representations, arXiv 2020
- Chiappa, Silvia, Ray Jiang, Tom Stepleton, Aldo Pacchiano, Heinrich Jiang, and John Aslanides. A general approach to fairness with optimal transport, AAAI 2020