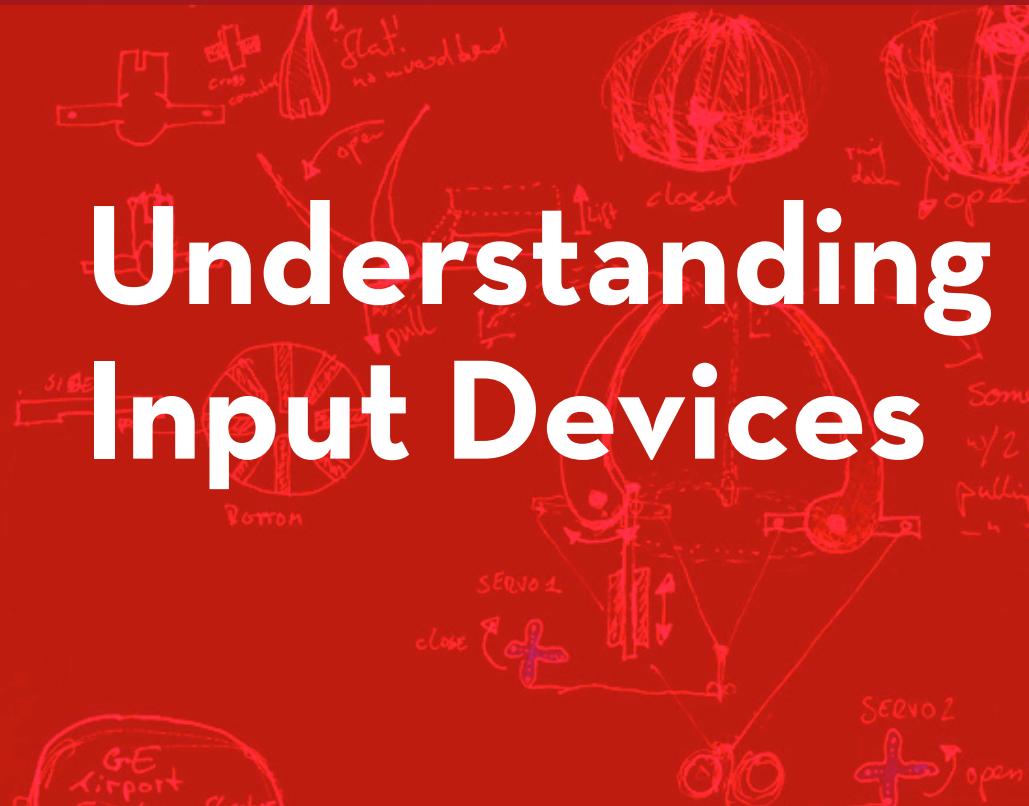
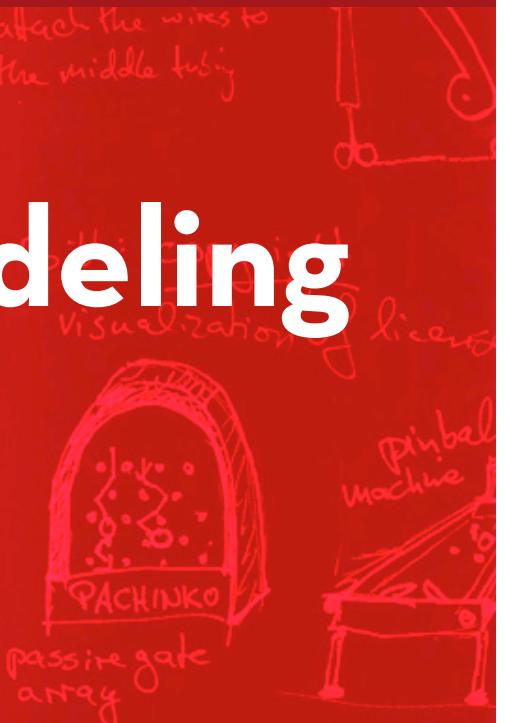


Understanding & Modeling Input Devices



attach the wires to
the middle tube



Scott: a gate that shows
who walked through it last

Bill: a gate that measures

Björn Hartmann
bjoern@eecs.berkeley.edu

Announcements

- HW3 rubric clarified

http://hci/courses/cs147/assignments/3_discovery.html

- Google groups

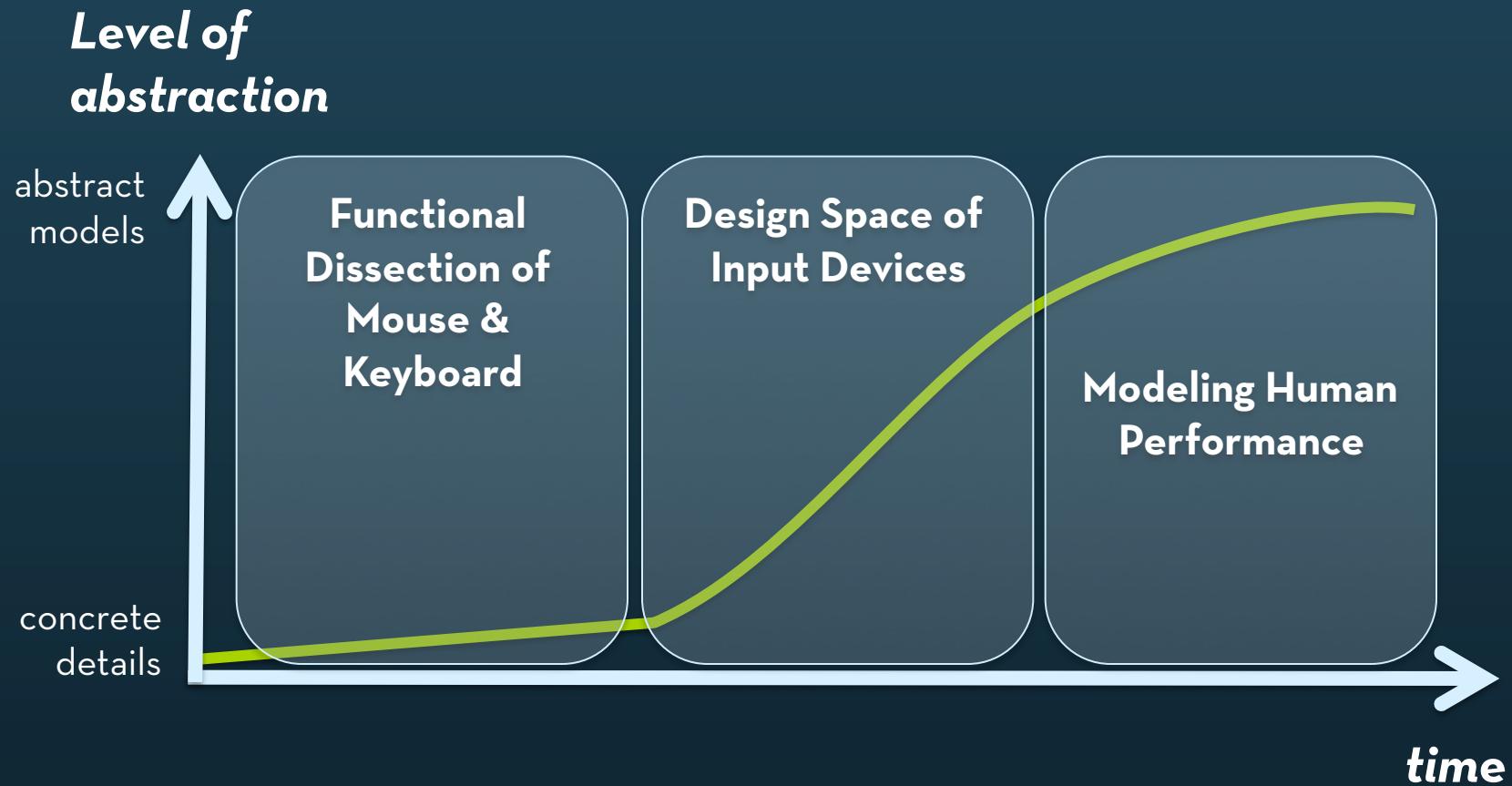
<http://groups.google.com/group/cs147-fall-2009/>

<http://groups.google.com/group/cs147-tech-2009/>

Questions for today

1. How do common input devices work?
2. How can we think about the larger space of all possible input devices?
3. Can we predict human input performance?
4. What about **uncommon** input devices (multitouch, tangible interfaces, ...)?
5. Will this be on the exam? Yes.

Today's lecture in graph form

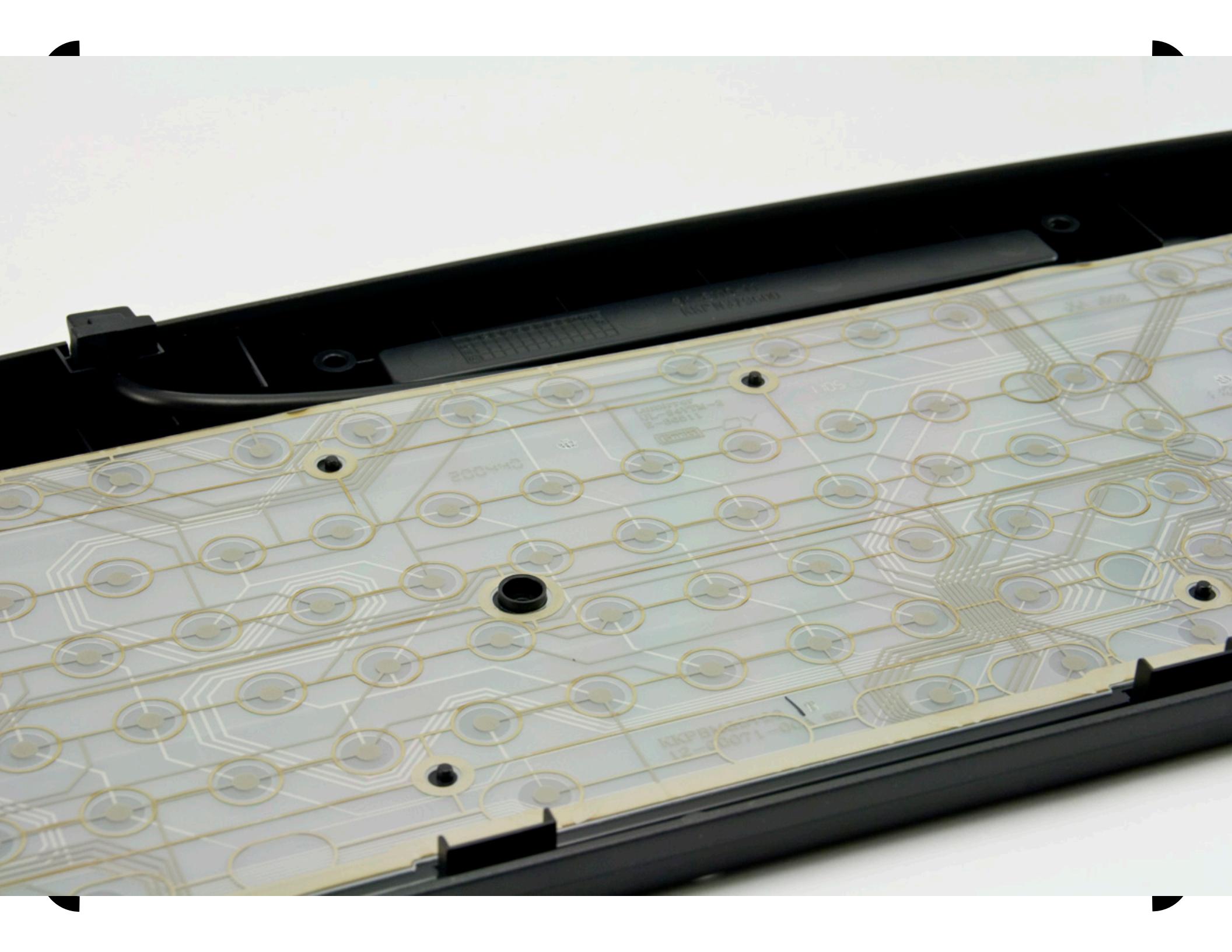


I think my keyboard is broken.

**Whenever I have a few keys pressed down,
some keys suddenly don't work anymore;
at other times 'phantom' characters appear.**

What's going on?





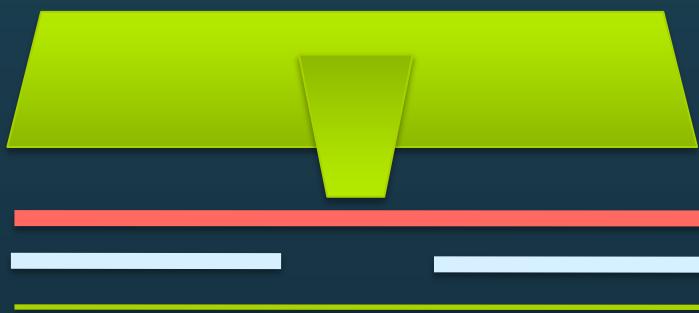
2004Н0

БАКИРС
12-0071-0

БАКИРС
12-0071-0

105

Separating layer
(with hole)



Key cap

Top conductive layer

Bottom conductive
layer



Separating layer
(with hole)



Key cap

Top conductive layer

Bottom conductive
layer

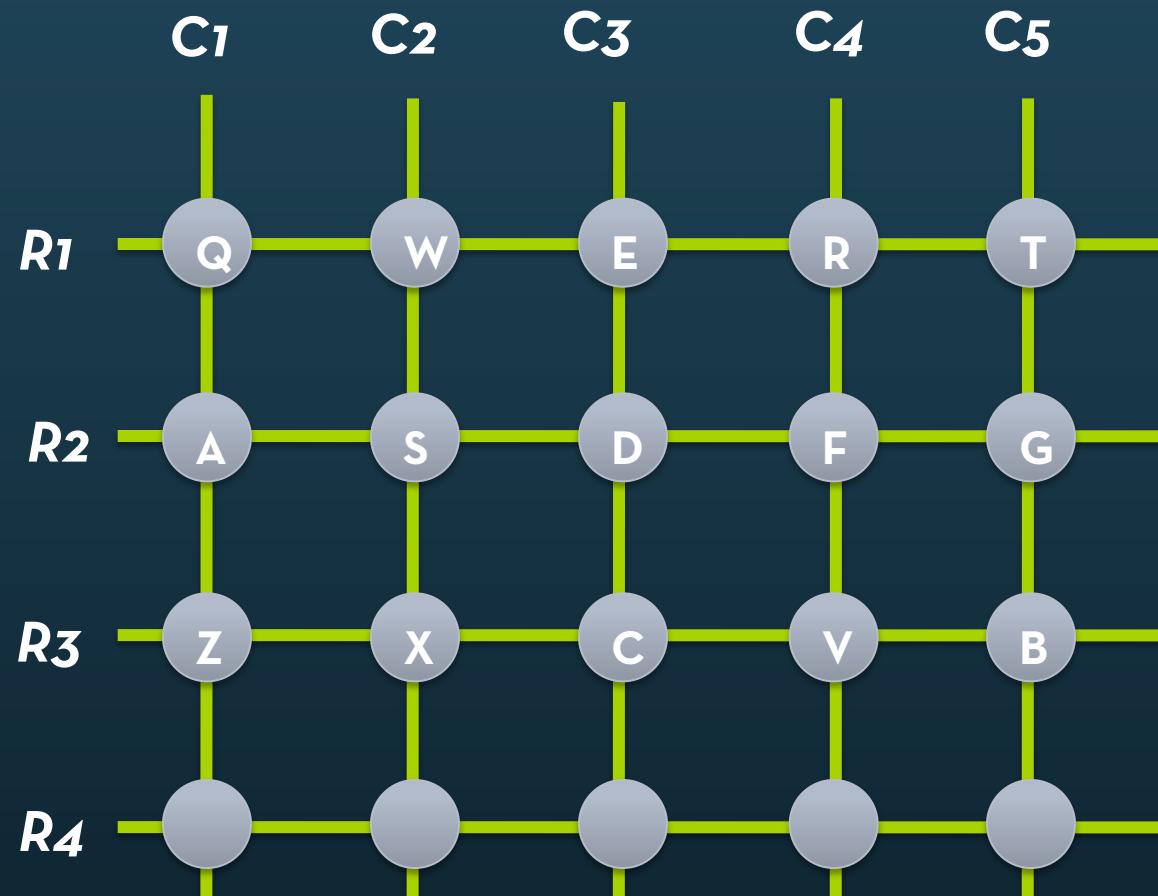




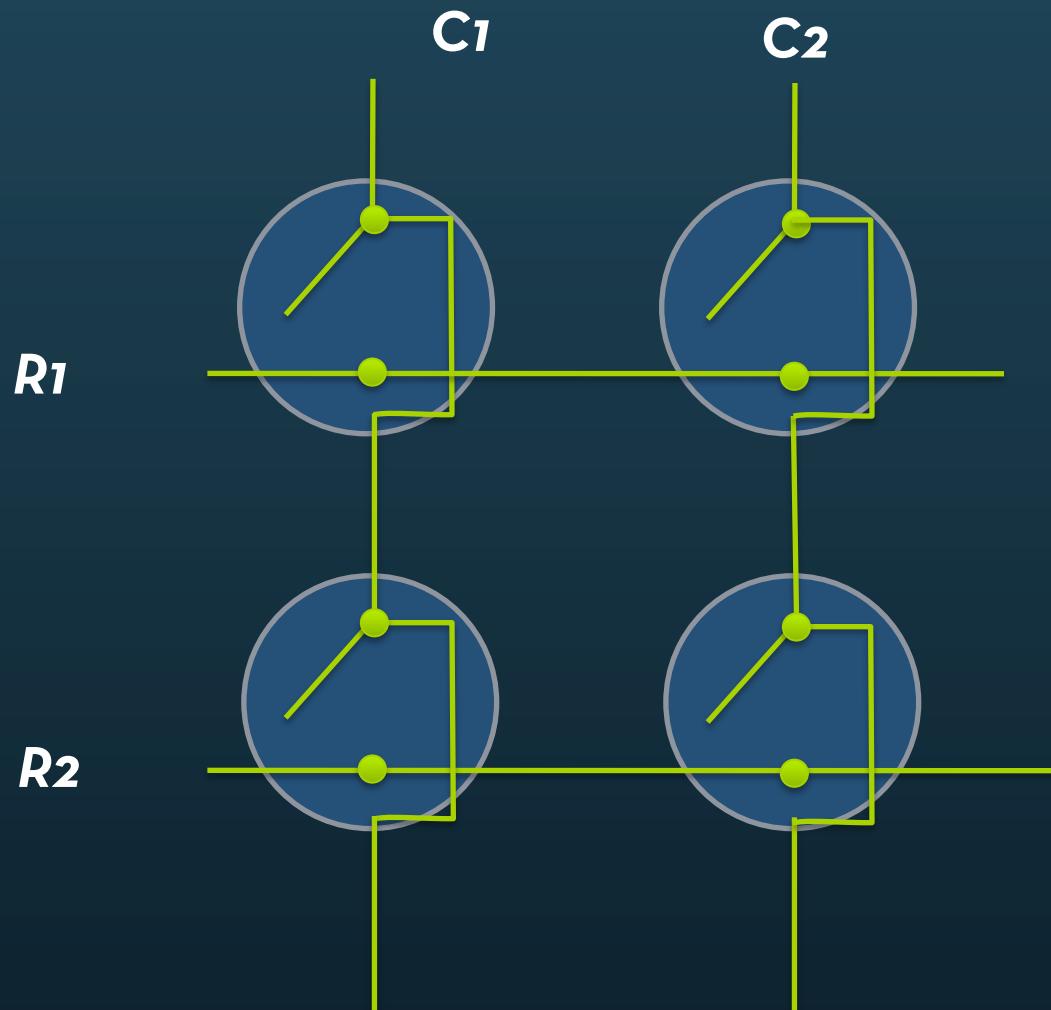
Row/Column Scanning

9 lines

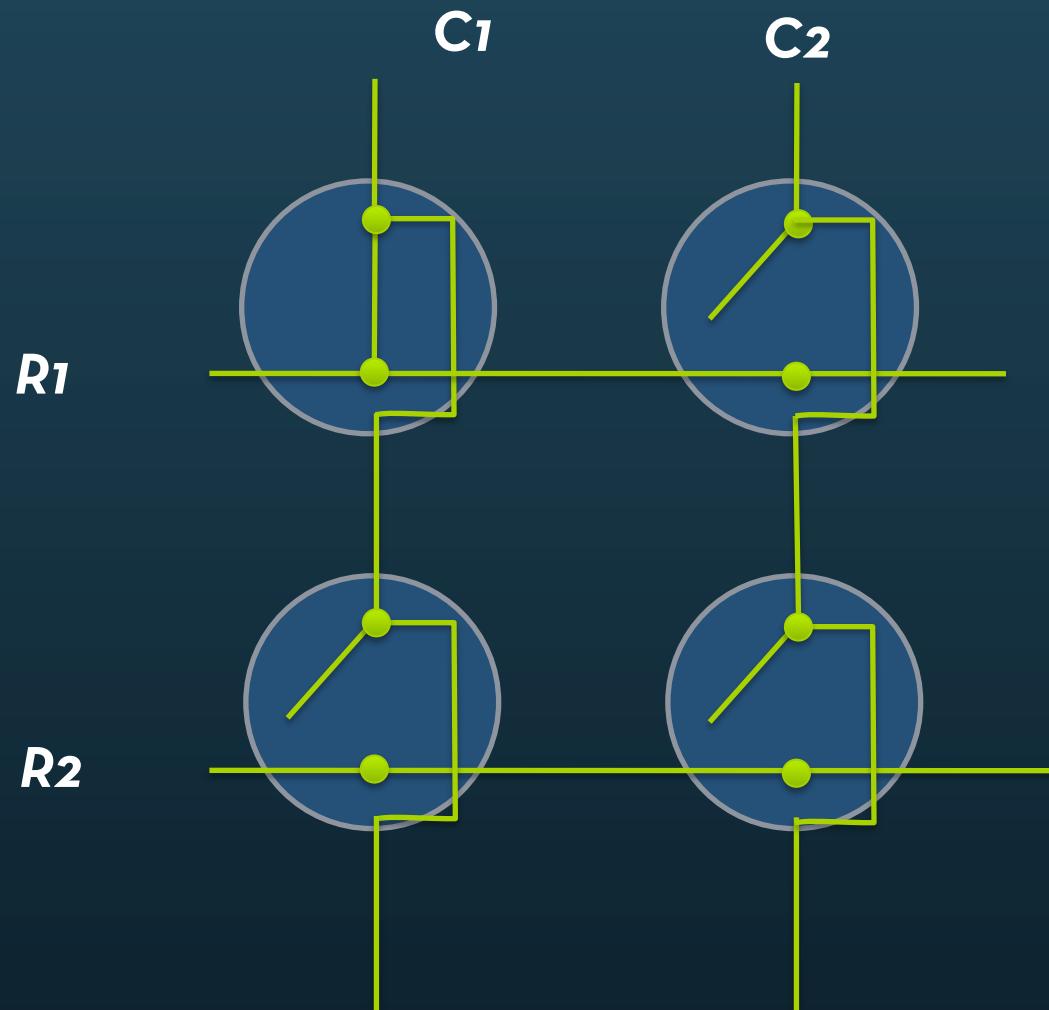
20 keys



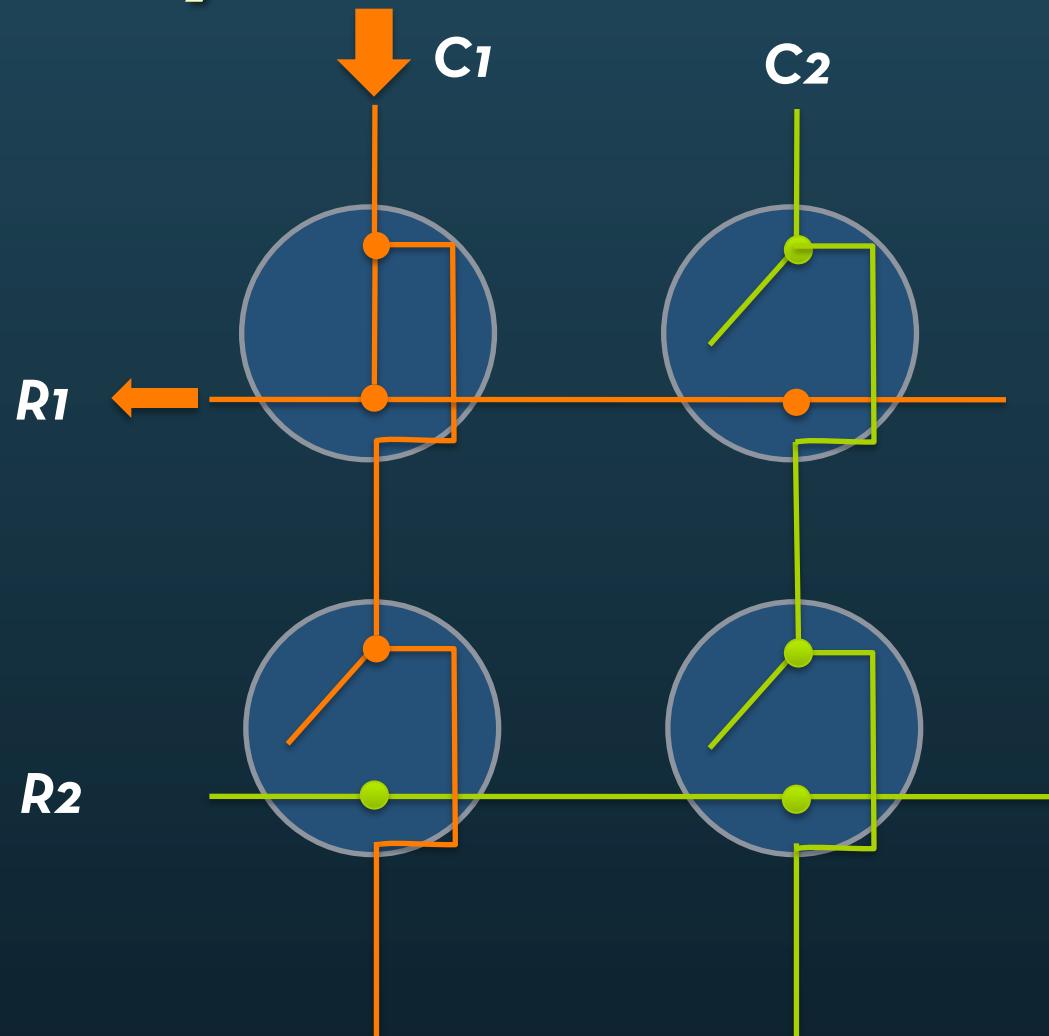
Closeup



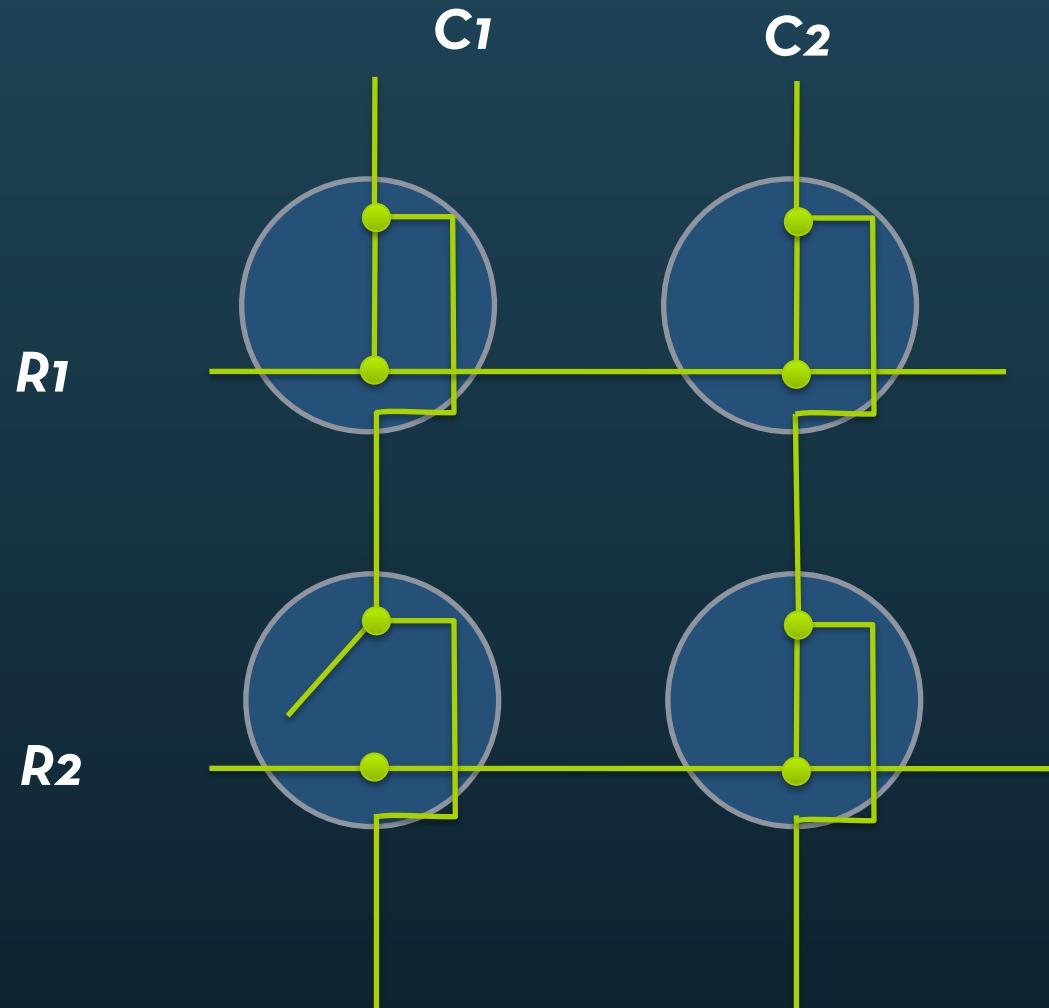
One Key Down



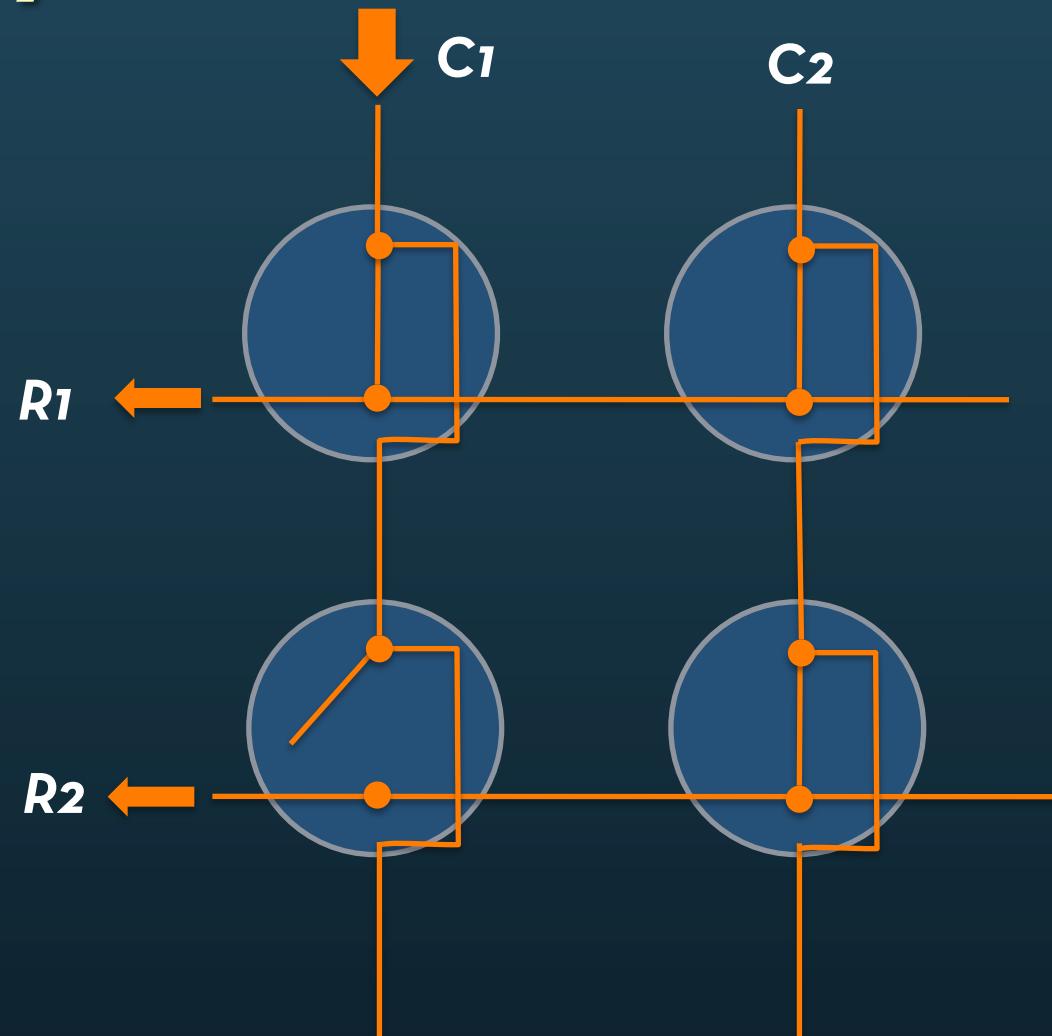
One Key Down



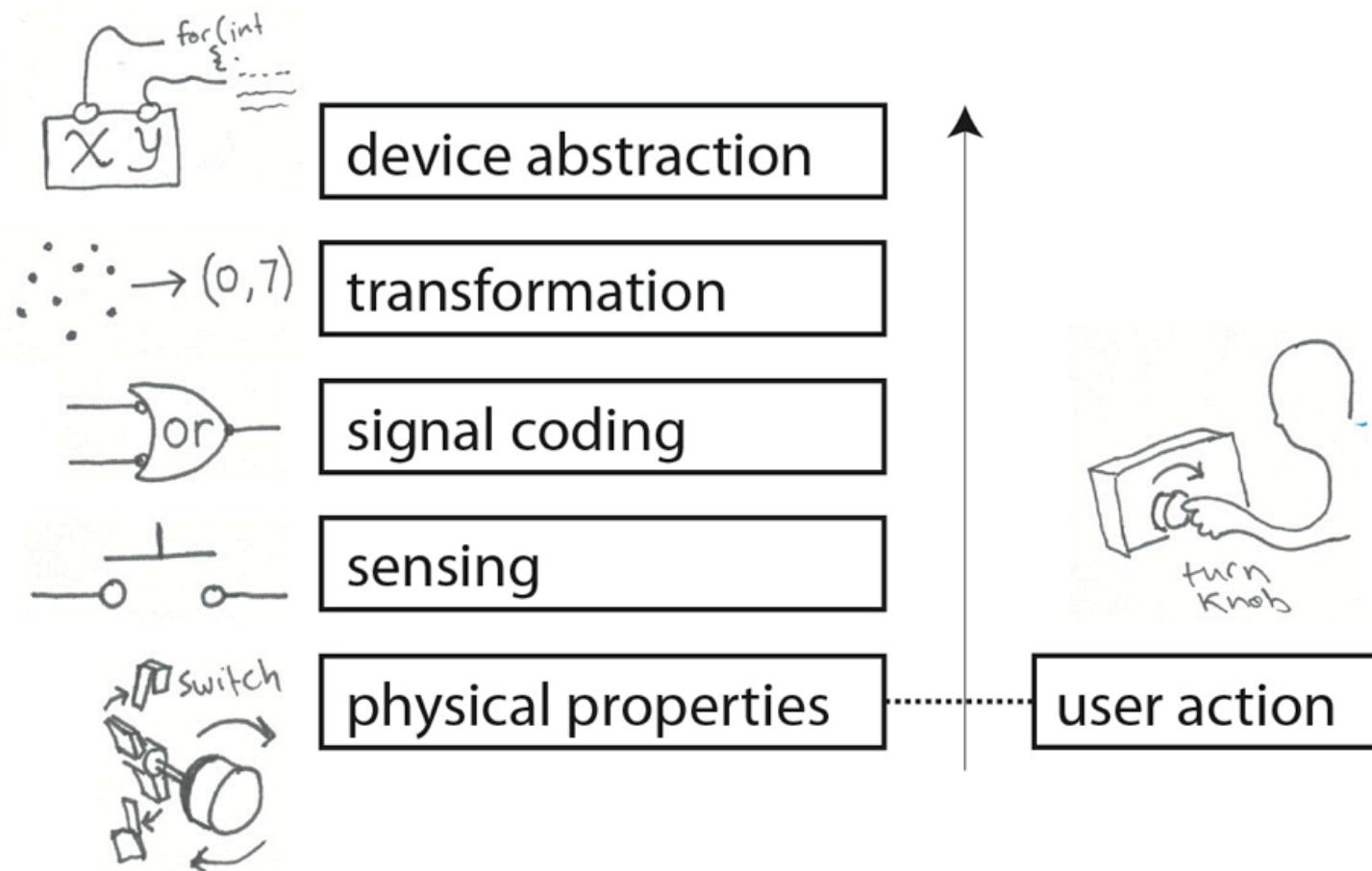
3 Keys Down

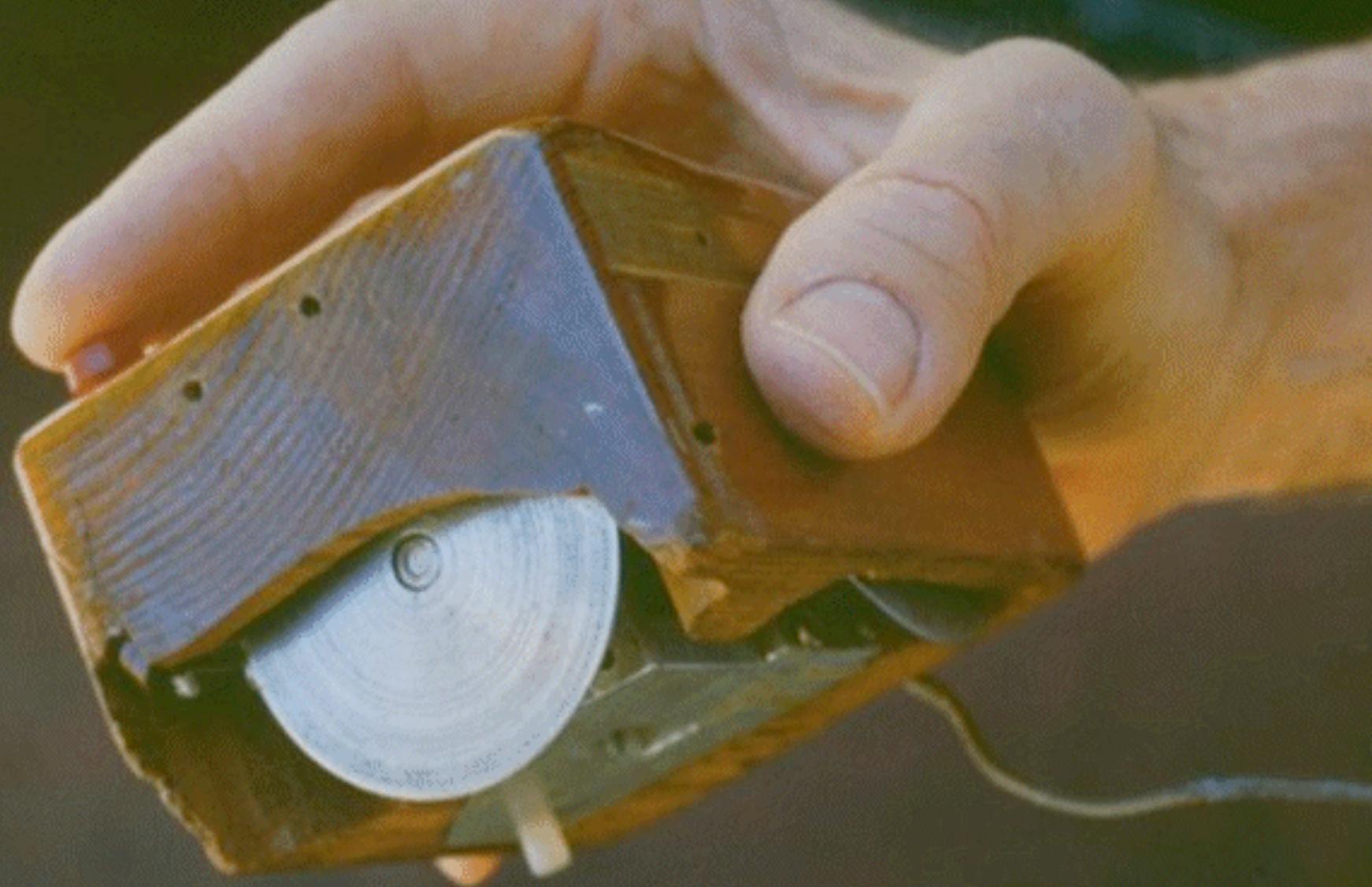


3 Keys Down



A Layered Framework



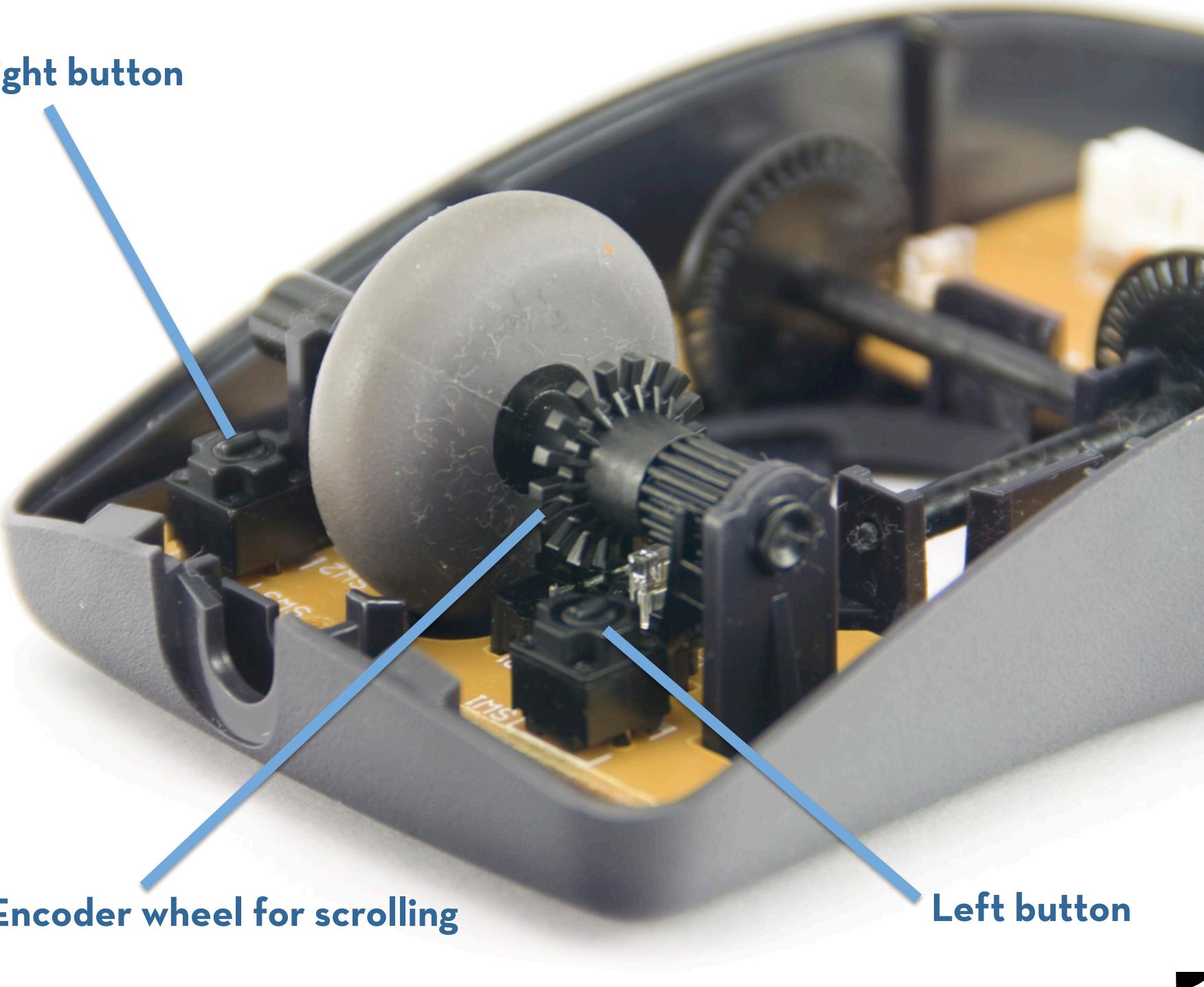


Mouse. Engelbart and English ~1964

Source: Card, Stu. Lecture on Human Information Interaction. Stanford, 2007.







Right button

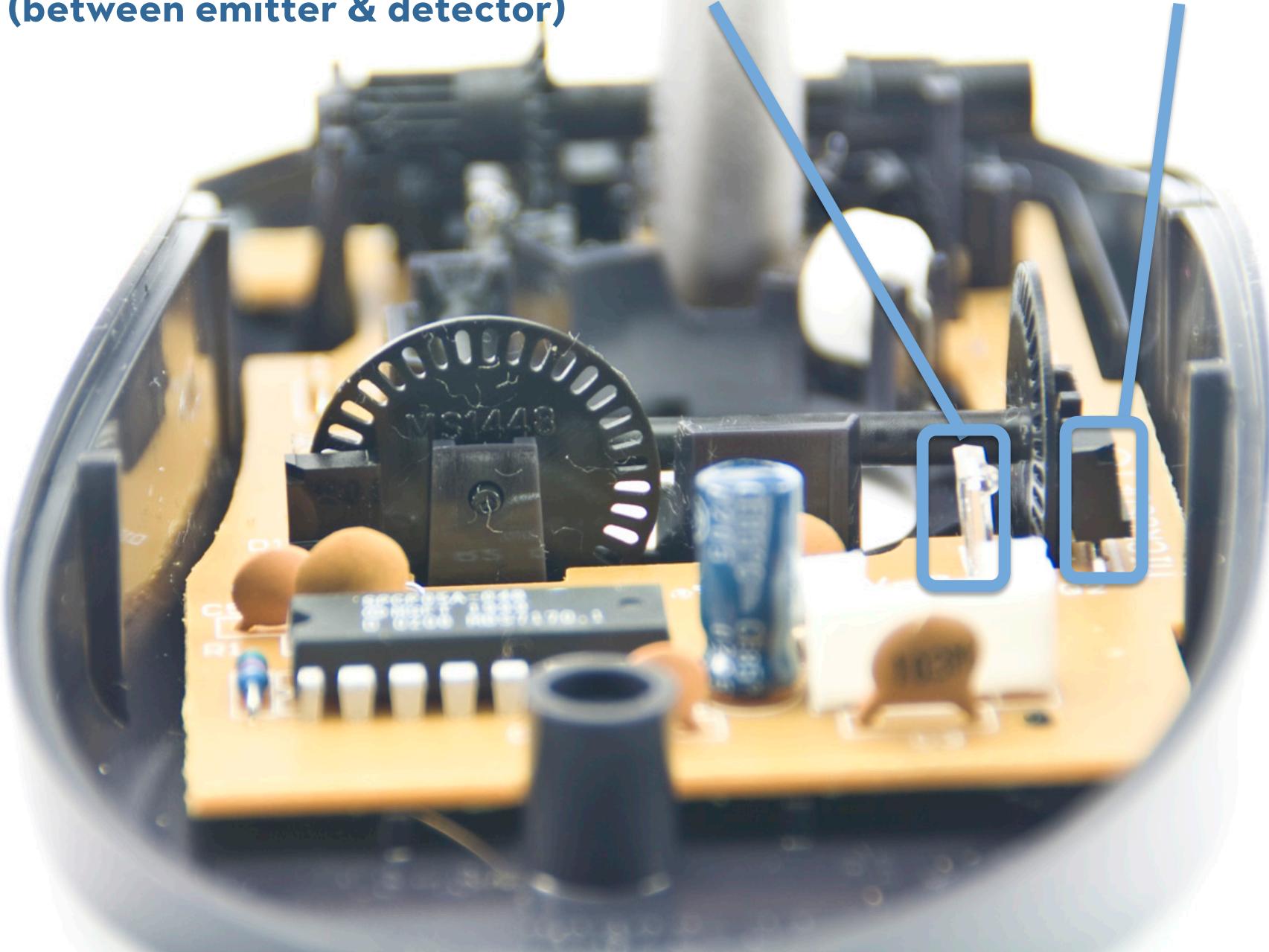
Encoder wheel for scrolling

Left button

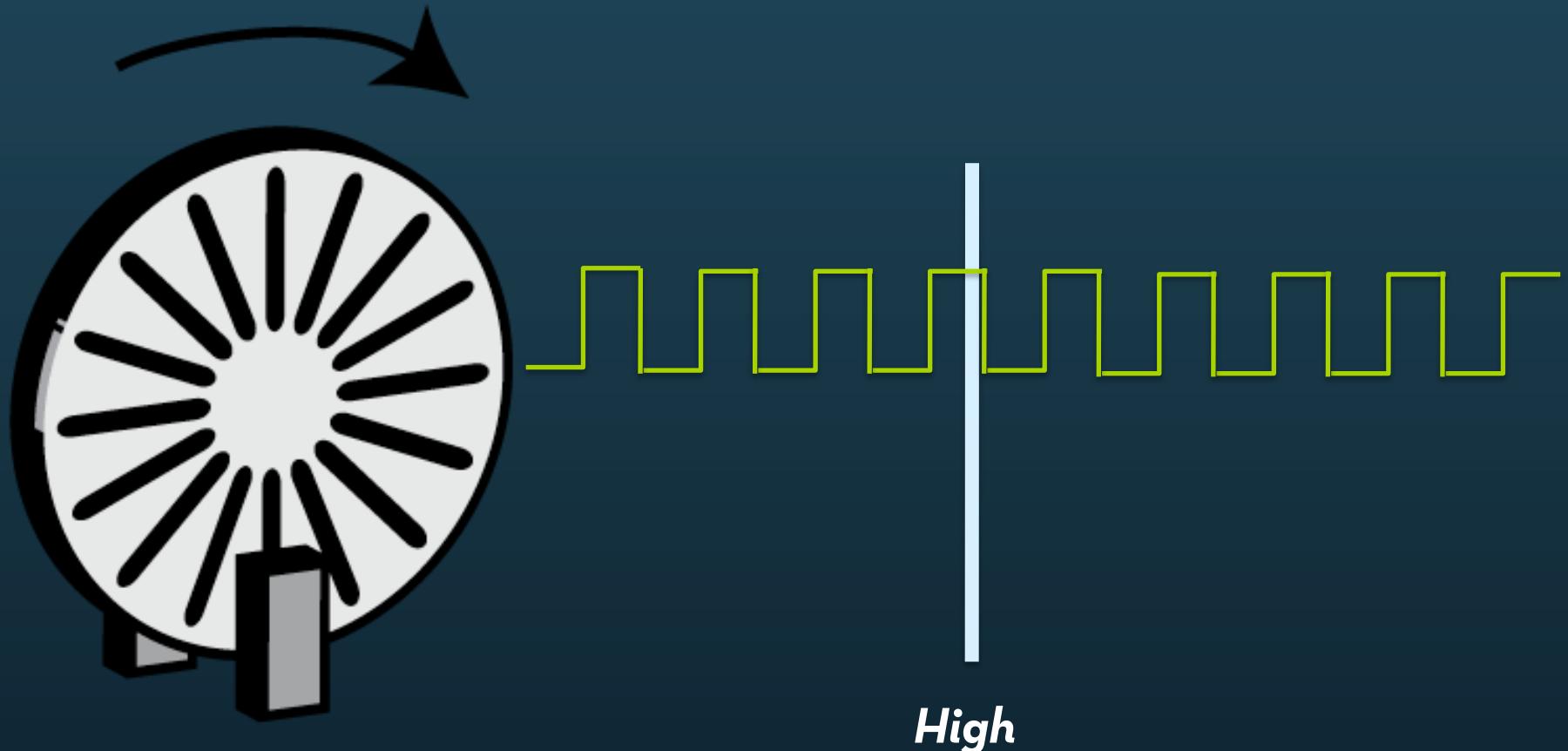
slotted wheel
(between emitter & detector)

IR emitter

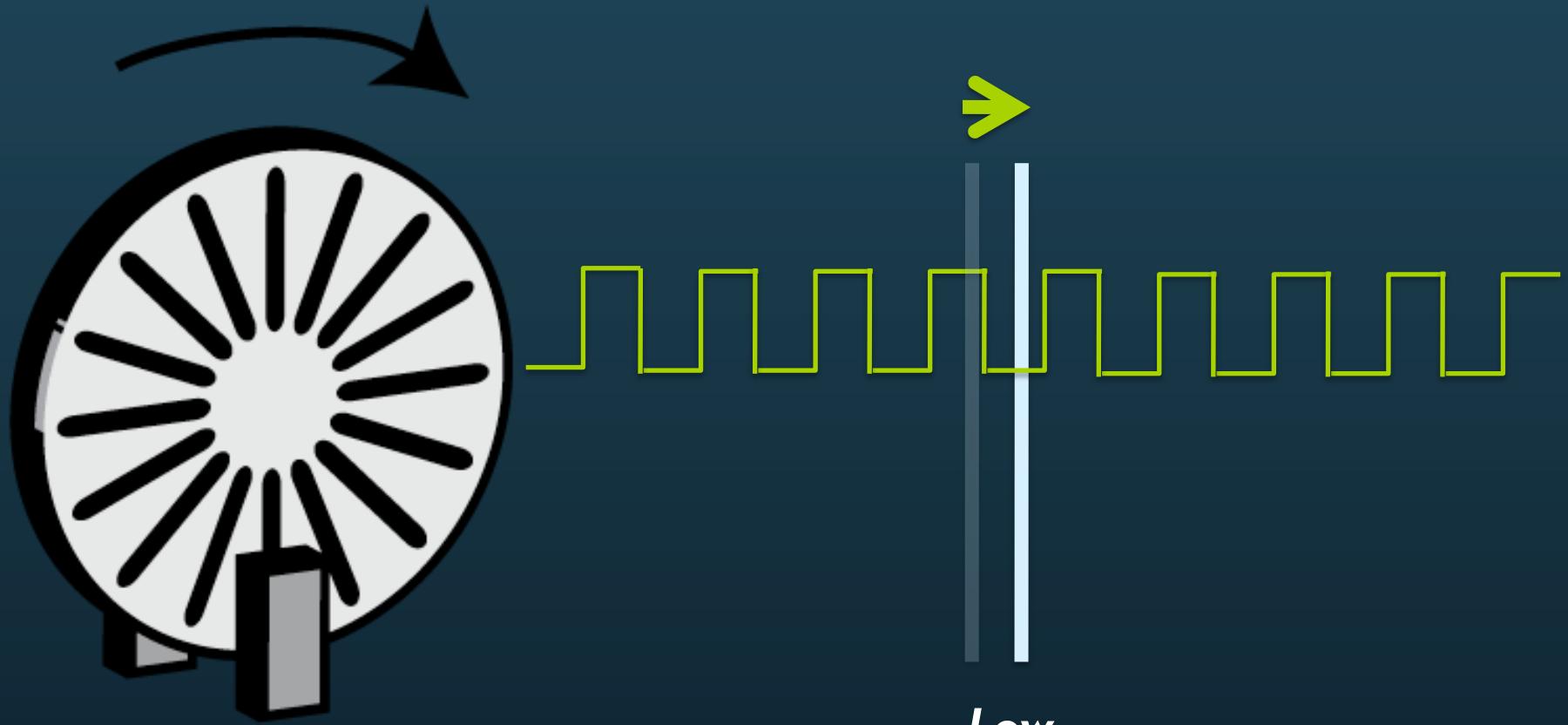
IR detector



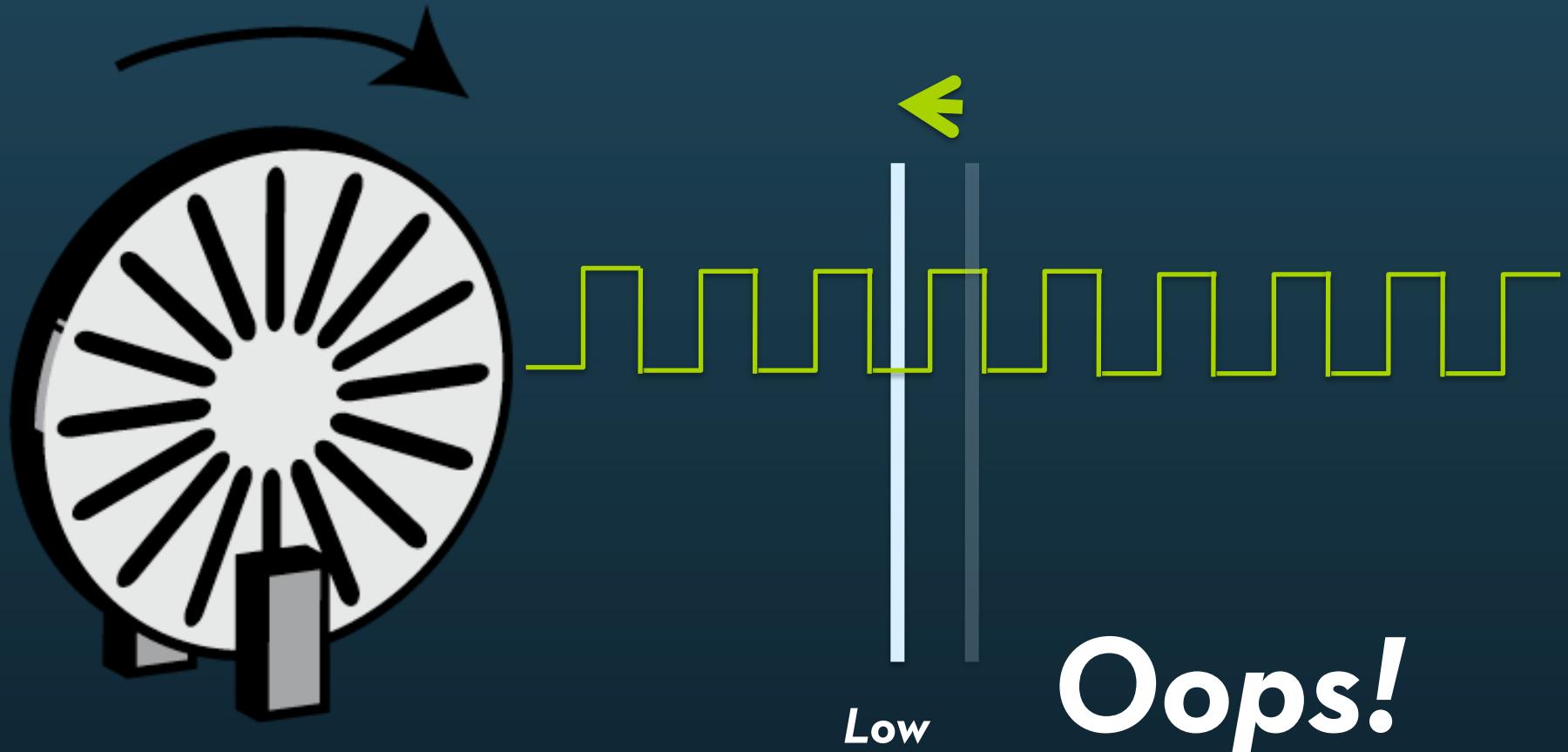
Sensing: Rotary Encoder



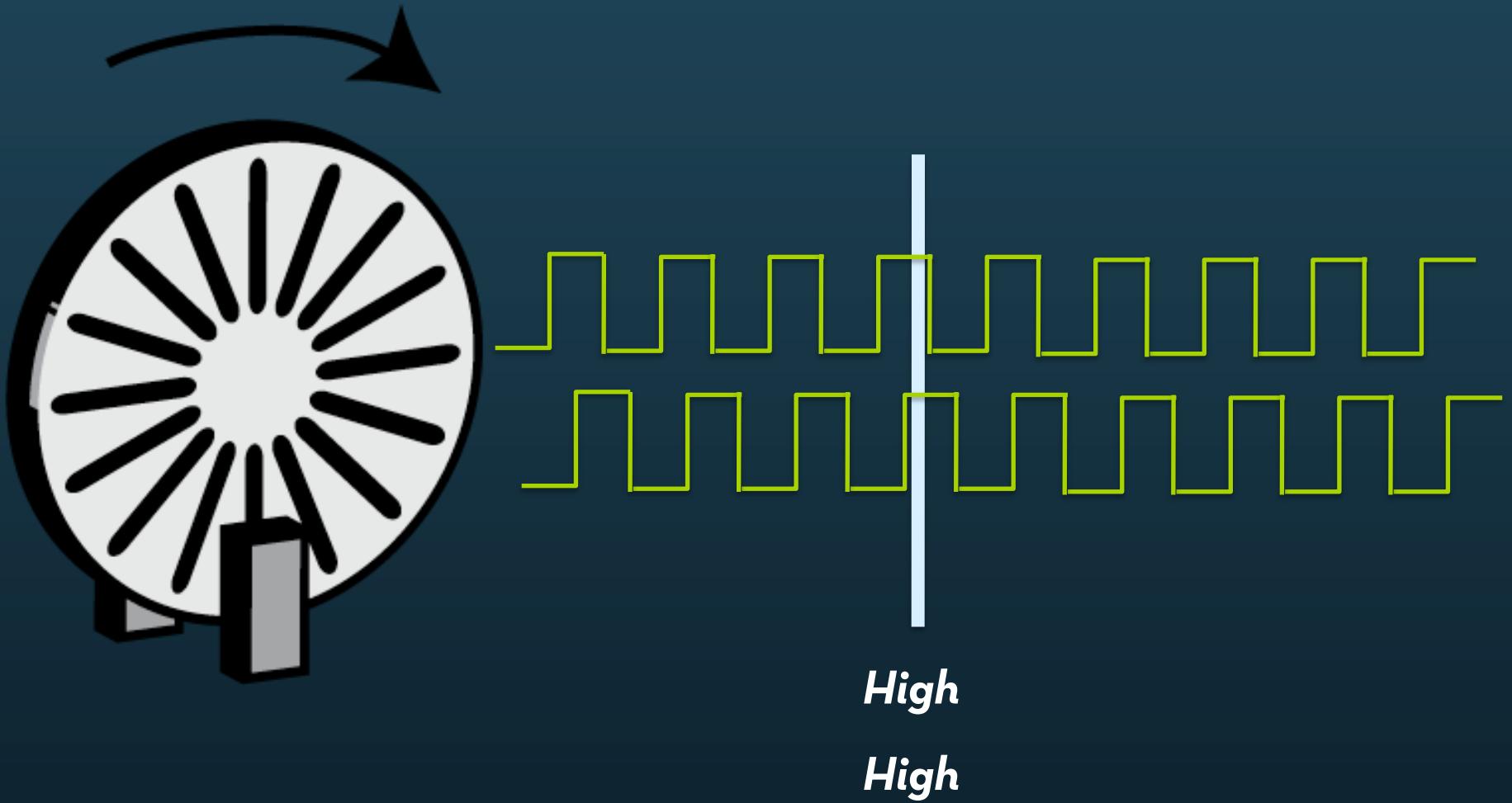
Sensing: Fwd Rotation



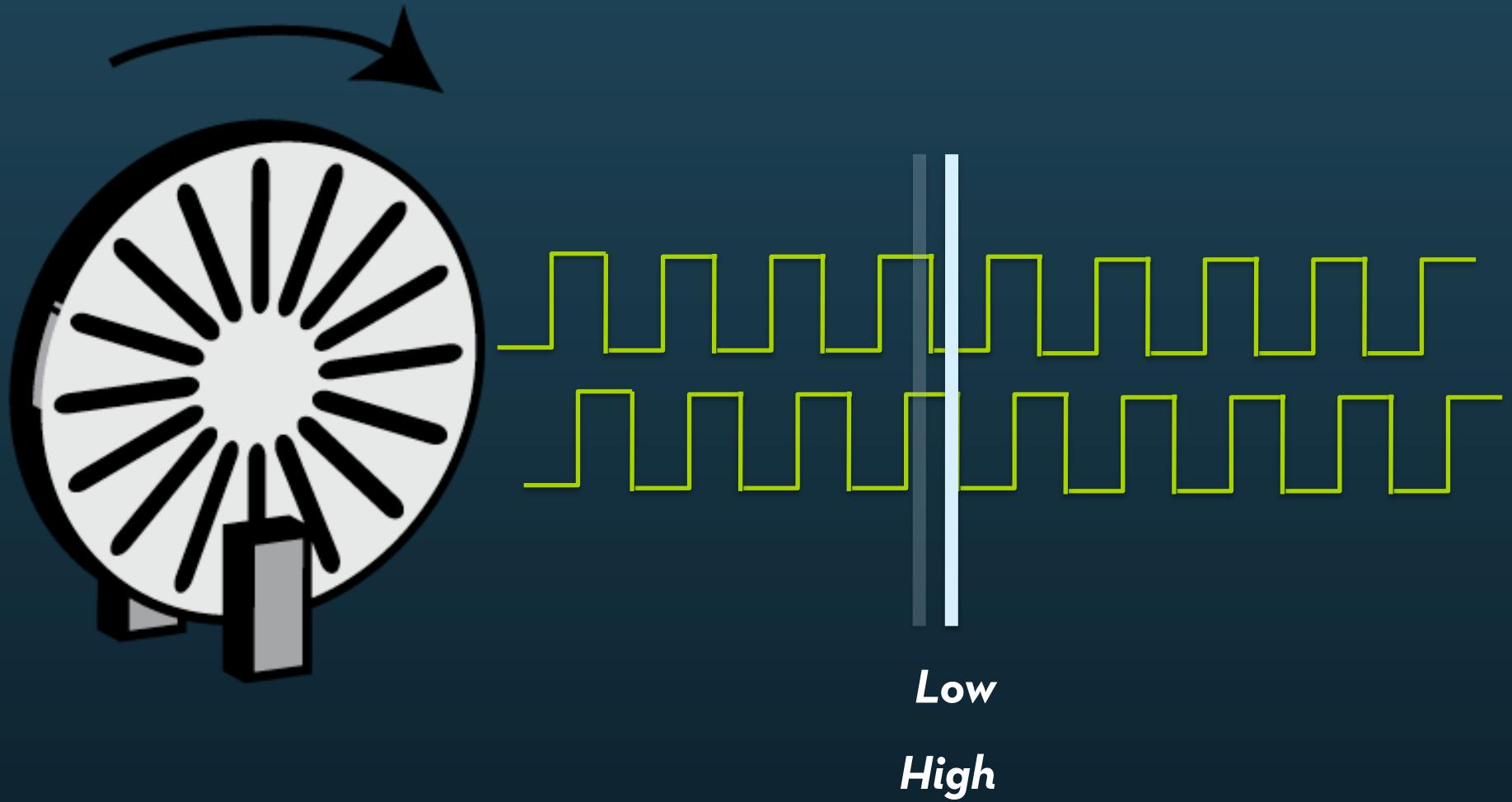
Sensing: Backwd Rotation



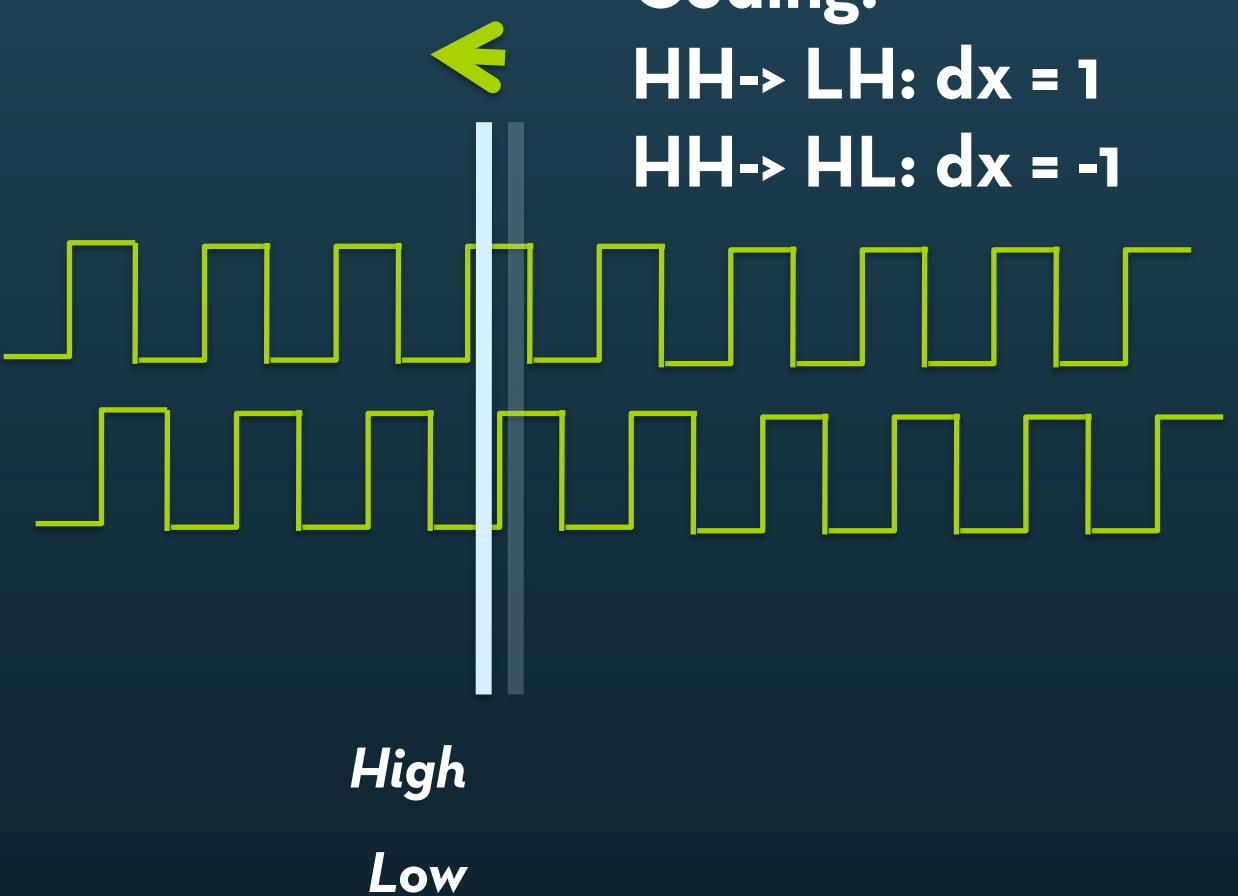
Solution: Use two out-of-phase detectors



Sensing: Rotary Encoder



Sensing: Rotary Encoder



Transformation

$$cx_t = \max(0, \min(sw, cx_{t-1} + dx * cd))$$

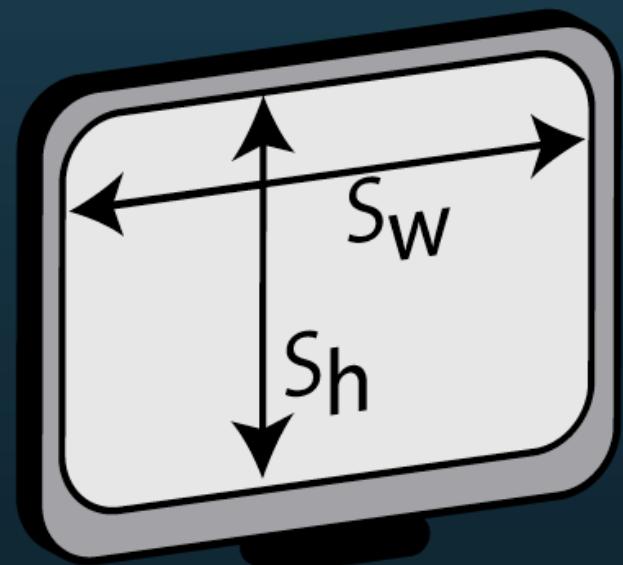
$$cy_t = \dots$$

cx_t : cursor x position in screen coordinates at time t

dx: mouse x movement delta in mouse coordinates

sw: screen width

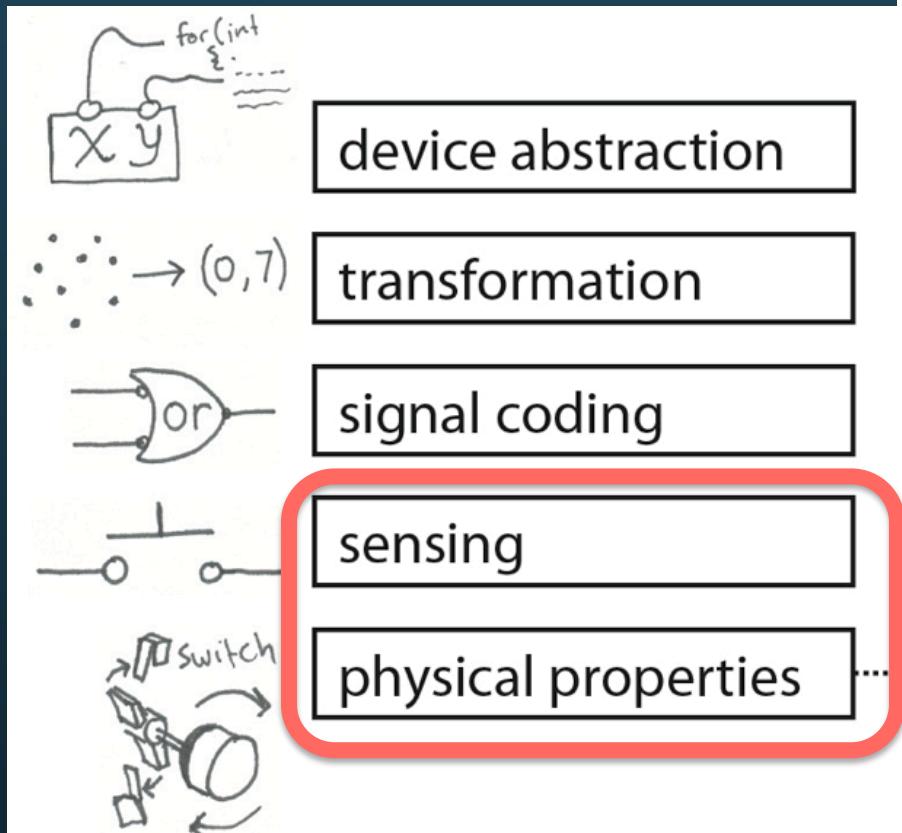
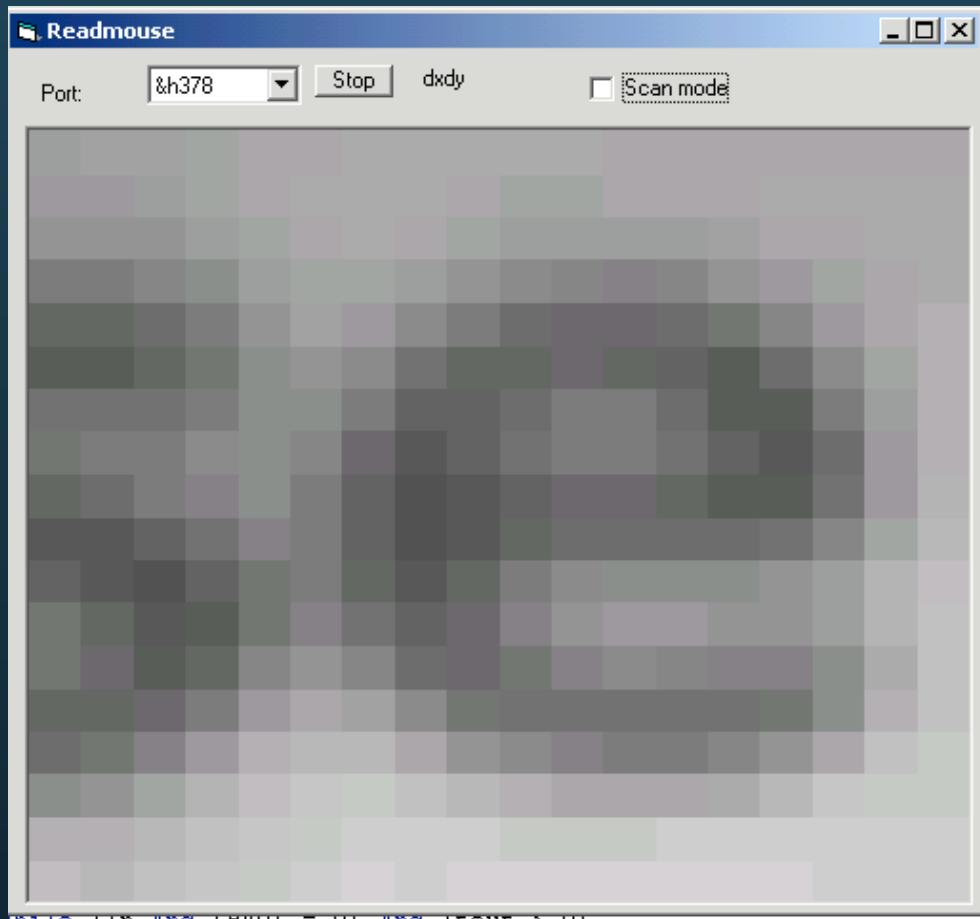
cd: control-display ratio



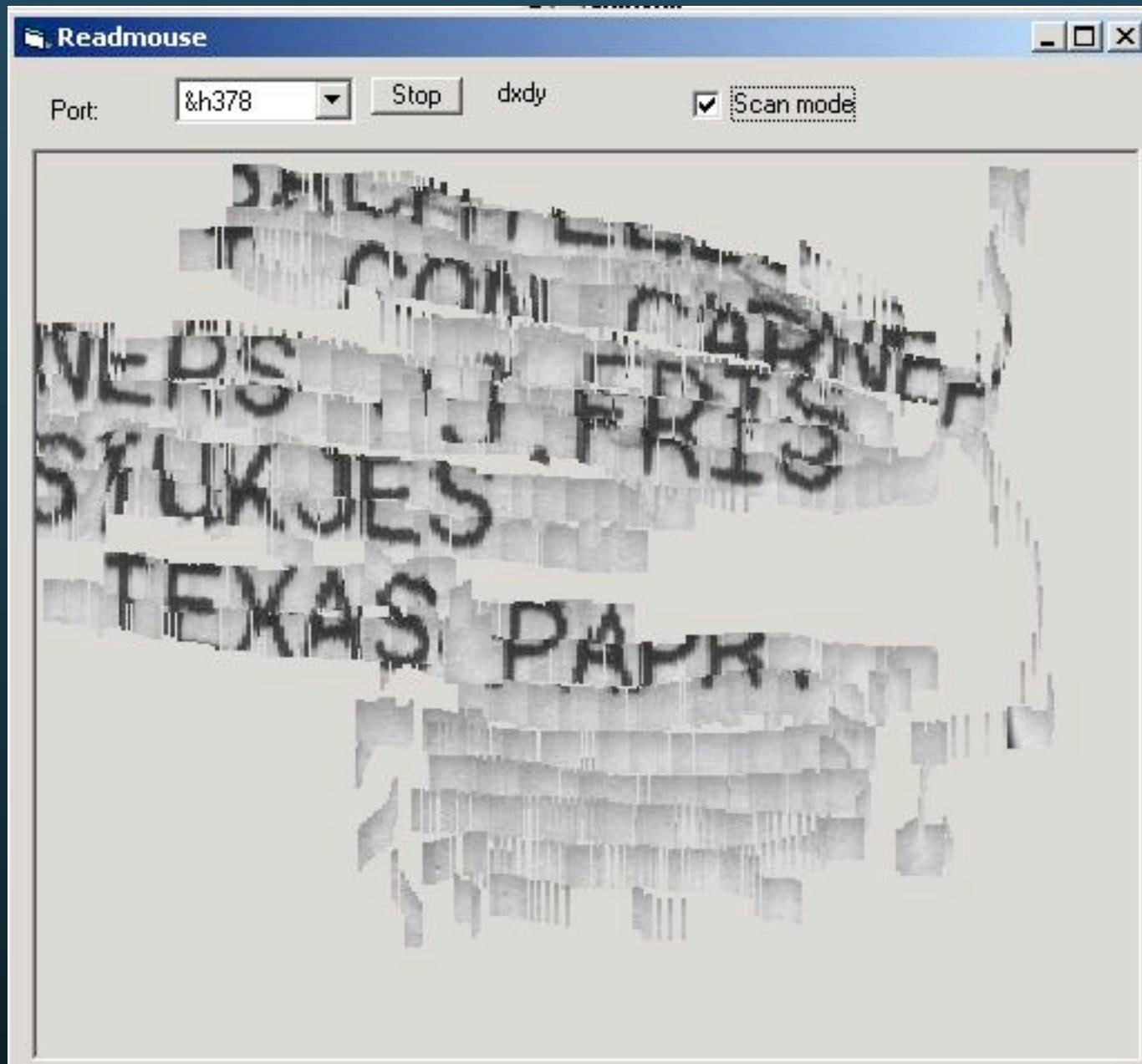
Device Abstraction

- Click, DoubleClick, MouseUp, MouseDown, MouseMove ...

What about optical mice?



Source: <http://spritesmods.com/?art=mouseeye>



Source: <http://spritesmods.com/?art=mouseeye>

Trackball, Trackpad



Trackpoint

- Indirect, force sensing, velocity control
- Nonlinear transfer function



Joysticks



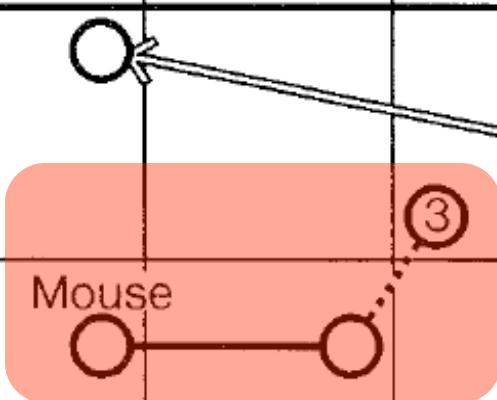
A design space of input devices...

Table I. Physical Properties Used by Input Devices

	Linear	Rotary
Position		
Absolute	Position P	Rotation R
Relative	Movement dP	Delta rotation dR
Force		
Absolute	Force F	Torque T
Relative	Delta force dF	Delta torque dT

Card, S. K., Mackinlay, J. D., and Robertson, G. G. 1991.
A morphological analysis of the design space of input devices.
ACM TOIS 9, 2 (Apr. 1991), 99-122.

	Linear				Rotary				
	X	Y	Z		rX	rY	rZ		
Position	P								Angle
Movement	dP								Delta Angle
Force	F								Torque
Delta Force	dF								Delta torque
	1	10	100	Inf	1	10	100	Inf	1
Measure					Measure				Measure



Station

Selection

Volume

R

dR

T

dT

Measure

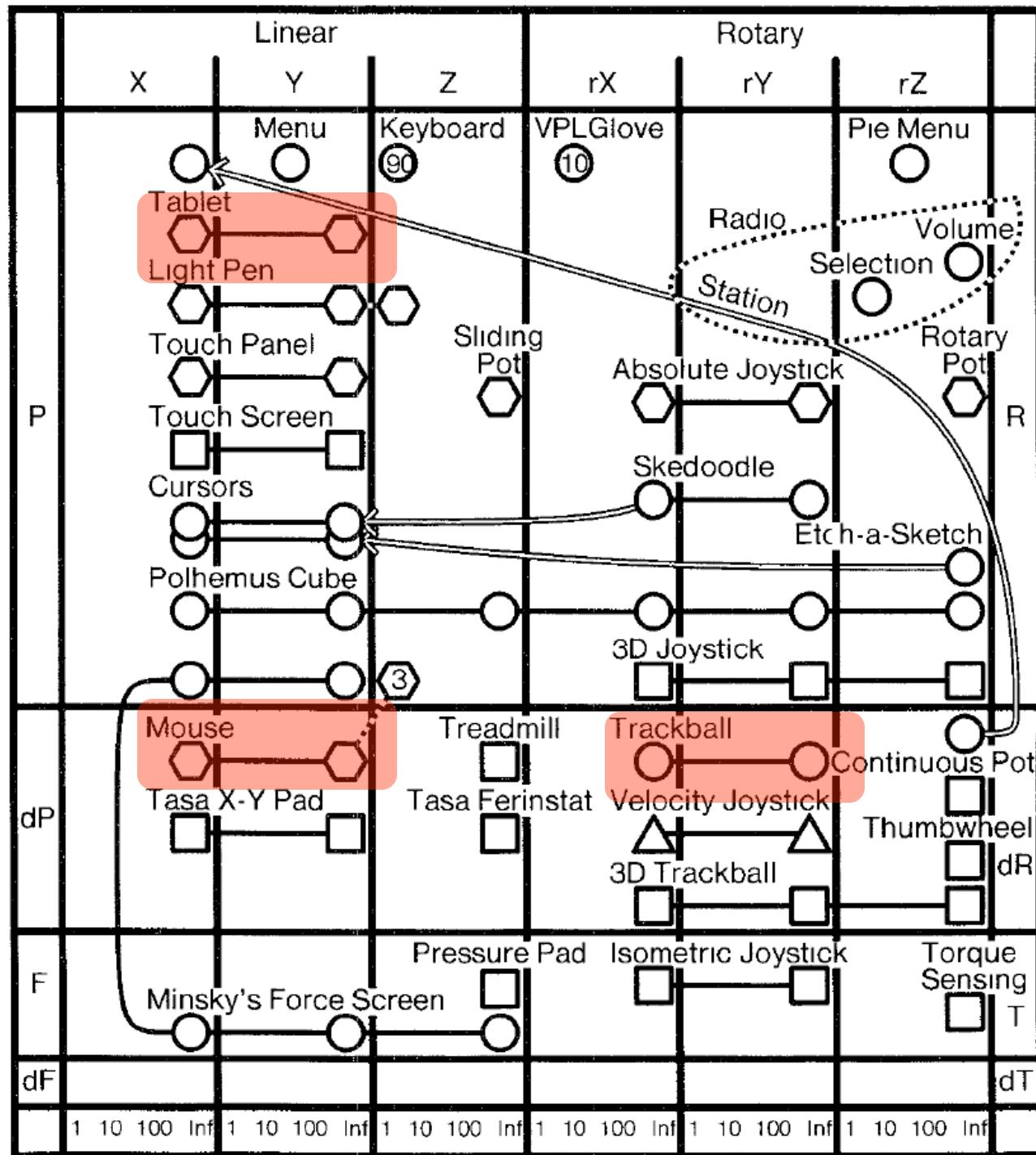
Measure

Measure

Measure

Measure

Measure



Which is faster?

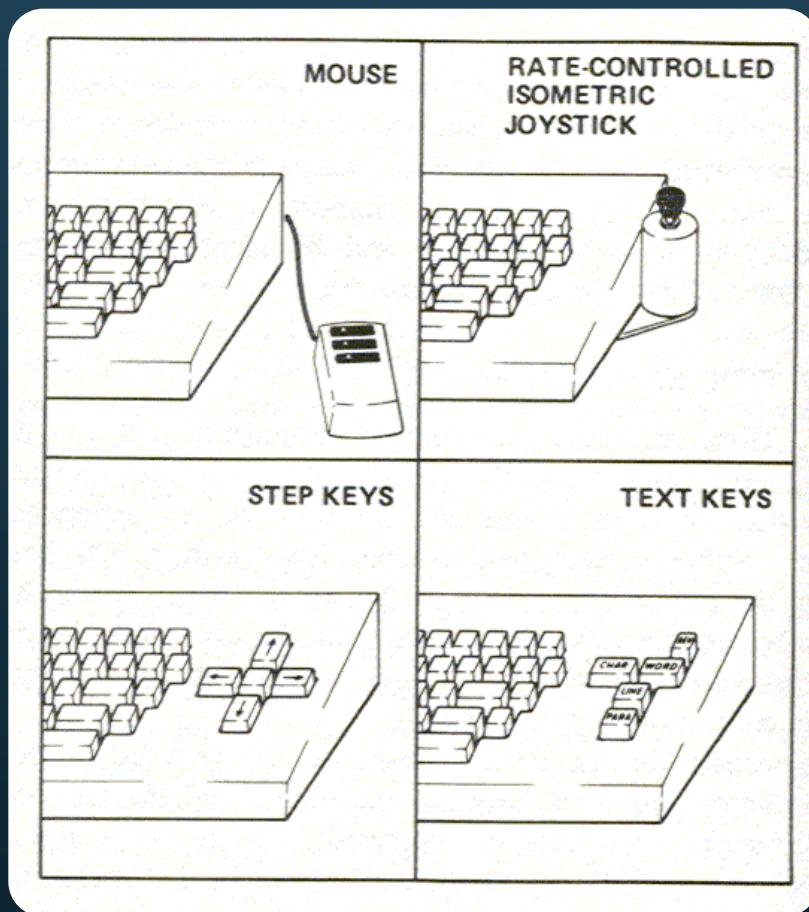


Source: Card, Stu. Lecture on Human Information Interaction. Stanford, 2007.

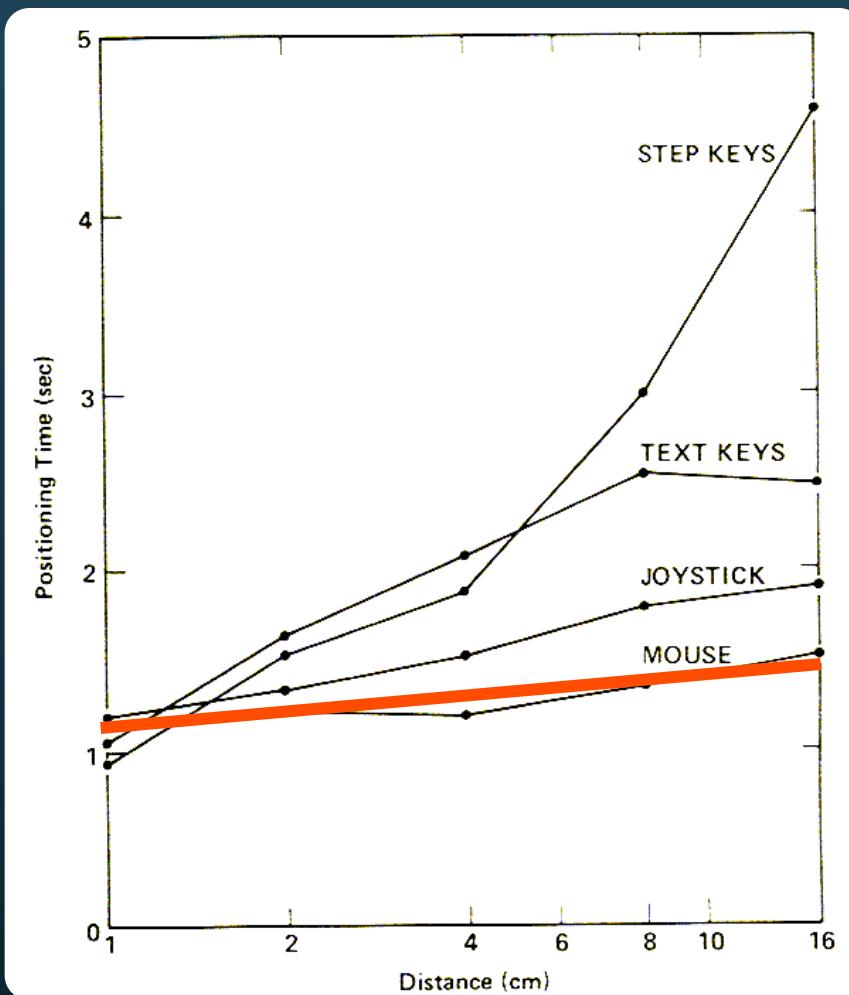
Which is faster?



Engelbart



Experiment: Mice are fastest!



Source: Card, Stu. Lecture on Human Information Interaction. Stanford, 2007.

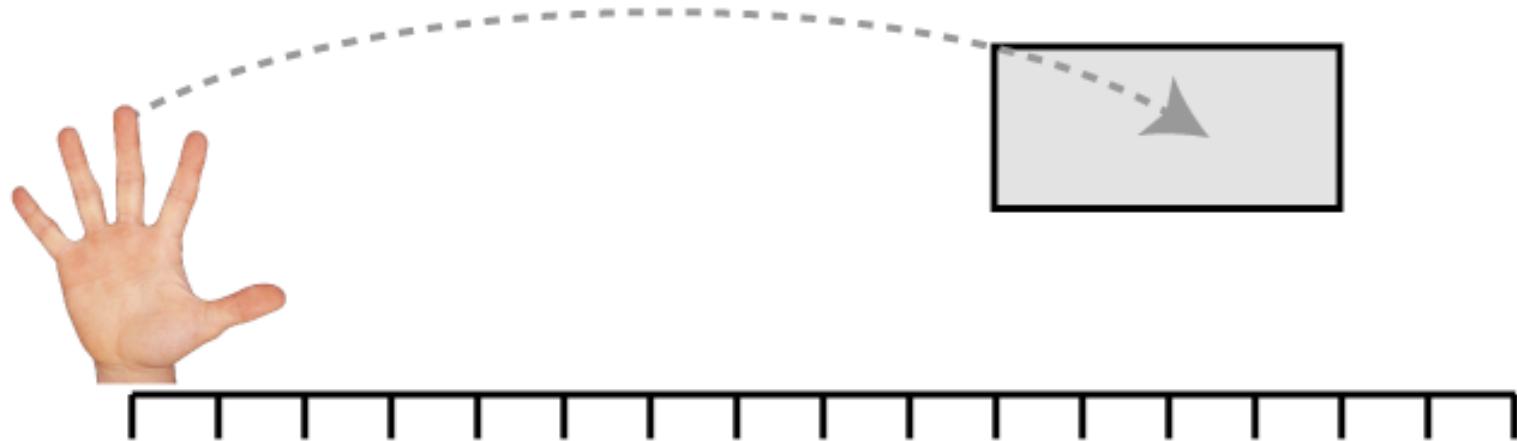
Fitts' Law

- Time T_{pos} to move the hand to target size S which is distance D away is given by:

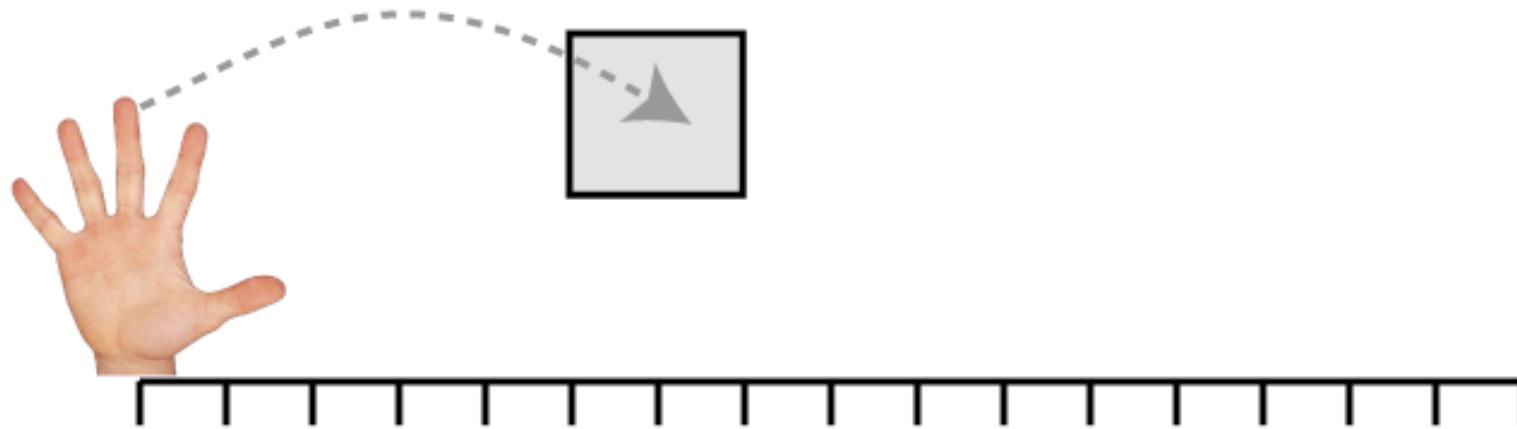
$$T_{\text{pos}} = a + b \underbrace{\log_2 (D/S + 1)}_{\text{Index of Difficulty (ID)}}$$

Only **relative precision** matters

$S = 4, D = 12$



$S = 2, D = 6$



Fitts' Law

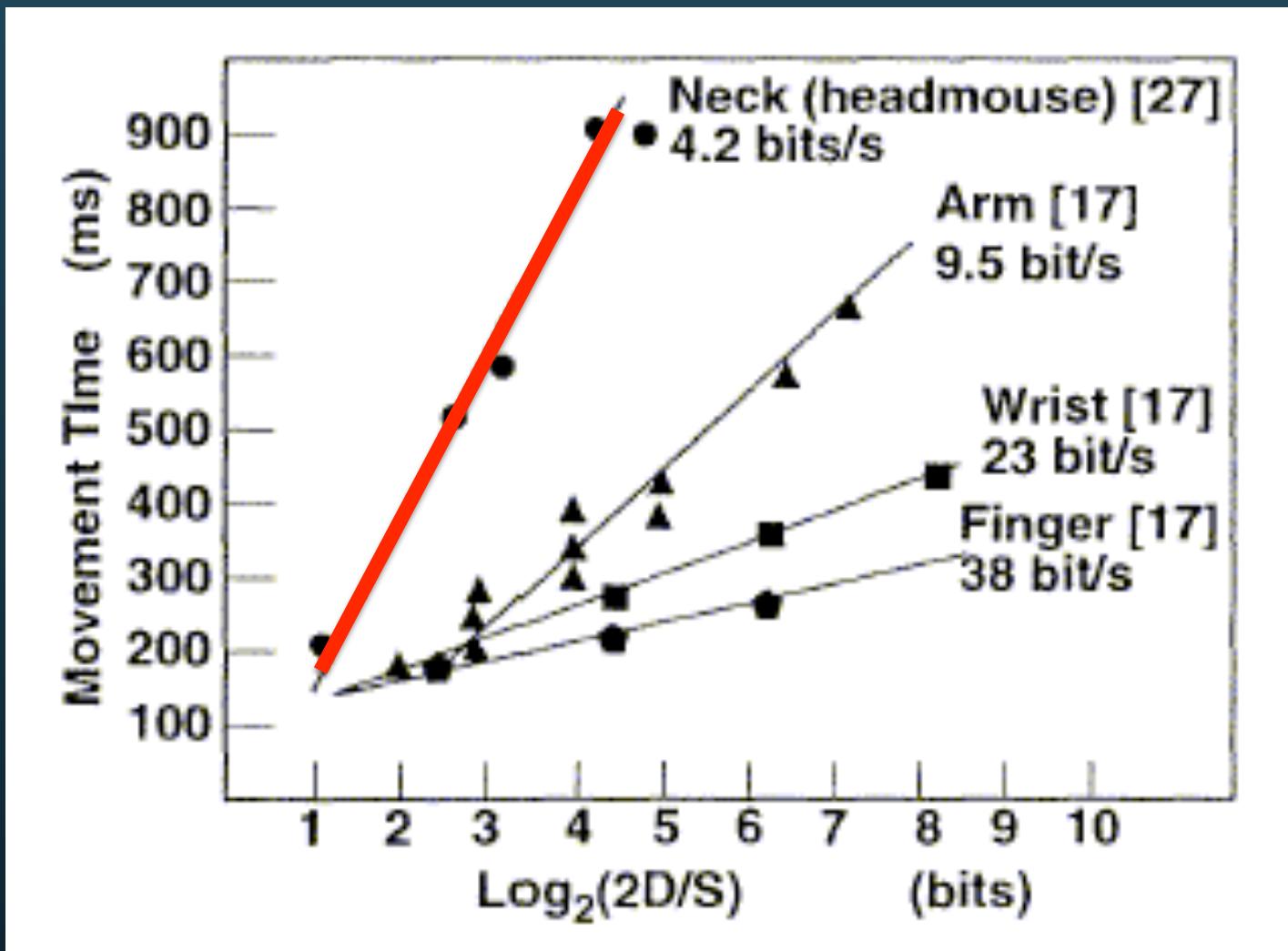
- Time T_{pos} to move the hand to target size S which is distance D away is given by:

$$T_{\text{pos}} = \underbrace{a + b}_{\text{Device Characteristics}} \log_2 (D/S + 1)$$

*Device Characteristics
(bandwidth of human muscle group & of device)*

*a: start/stop time
b: speed*

Bandwidth of Human Muscle Groups



Why is the mouse fastest?



Why these results?

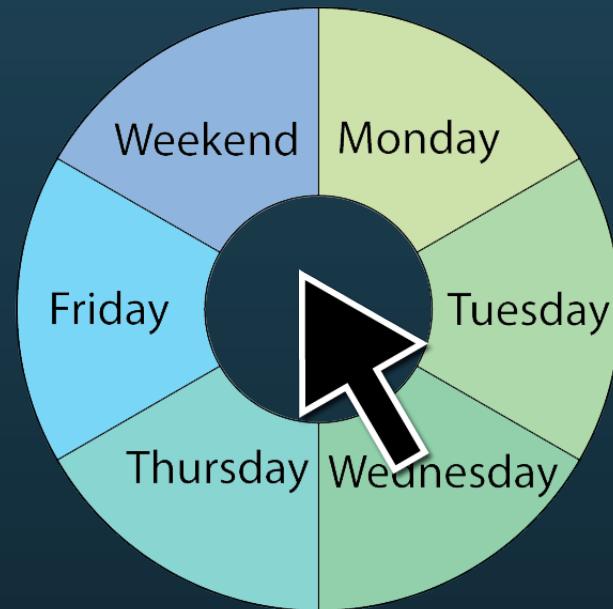
Time to position mouse proportional to Fitts' Index of Difficulty I_D .

[i.e. how well can the muscles direct the input device]

Therefore speed limit is in the eye-hand system, not the mouse.

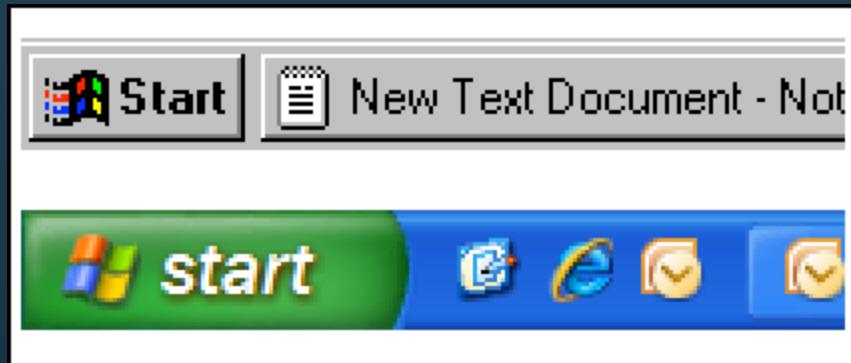
Therefore, mouse is a near optimal device.

Fitts' Law Example



- Which will be faster on average?
 - pie menu (bigger targets & less distance)

Fitts' Law in Windows & Mac OS



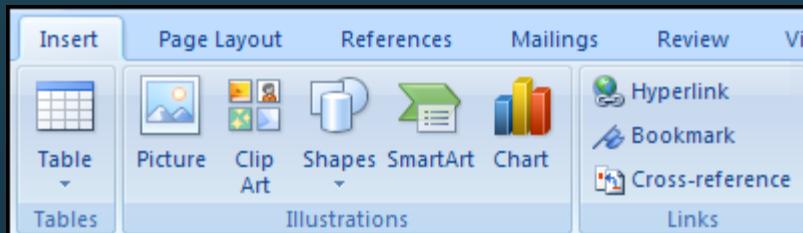
Windows 95: Missed by a pixel

Windows XP: Good to the last drop

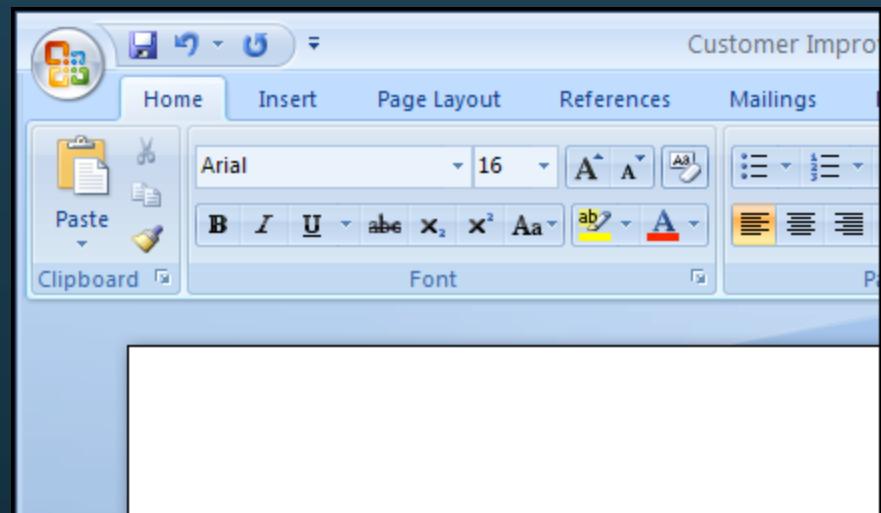


**The Apple menu in
Mac OS X v10.4 Tiger.**

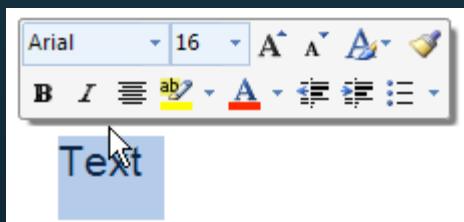
Fitts' Law in Microsoft Office 2007



Larger, labeled controls can be clicked more quickly



Magic Corner: Office Button in the upper-left corner



Mini Toolbar: Close to the cursor

Uncommon Input Devices

- Assumptions so far:
 - Single user, working in front of a desktop PC
 - Main tasks are typing and pointing
 - Efficiency rules
- What if we change these assumptions?
 - Design for enjoyment / engagement
 - Design for multi-user scenarios

Position+Orientation: Nintendo Wii



Source: Nintendo, us.wii.com

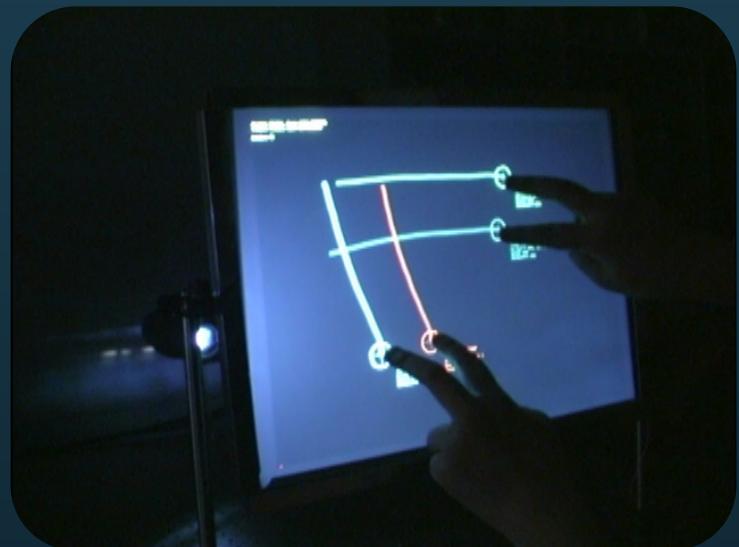
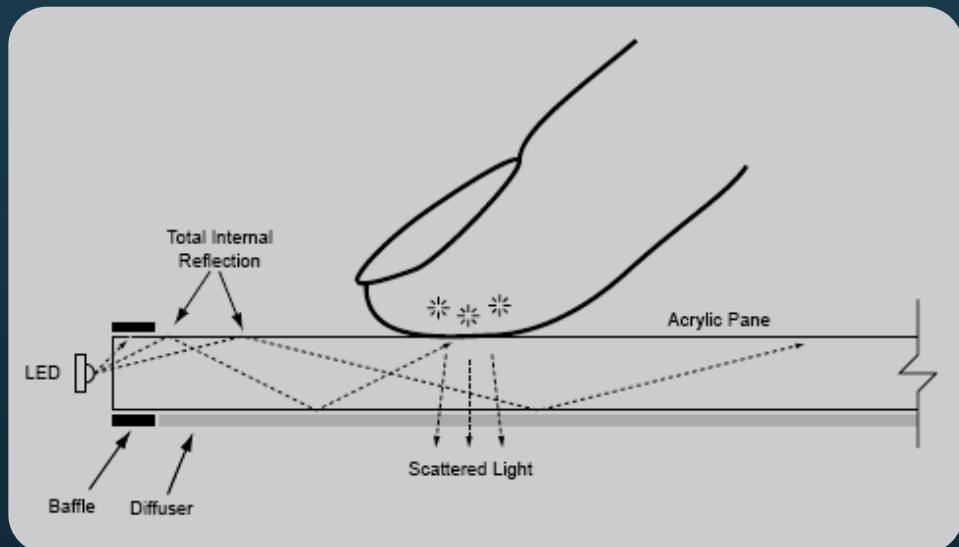
Camera-based input: IO Brush

I/O Brush

Ryokai & Marti
MIT Media Laboratory (C) 2005

Source: Kimiko Ryokai, <http://web.media.mit.edu/~kimiko/iobrush/>

Multi-touch



Jeff Han, Perceptive Pixel

Hybrids: Devices on Tables



Hartmann, Björn, Morris, M.R., Benko, H., and Wilson, A.
Augmenting Interactive Tables with Mice & Keyboards. In Proceedings of UIST 2009.

Hybrids: Devices on Tables



Hartmann, Björn, Morris, M.R., Benko, H., and Wilson, A.
Augmenting Interactive Tables with Mice & Keyboards. In Proceedings of UIST 2009.

Hybrids: Multi-touch on Mice

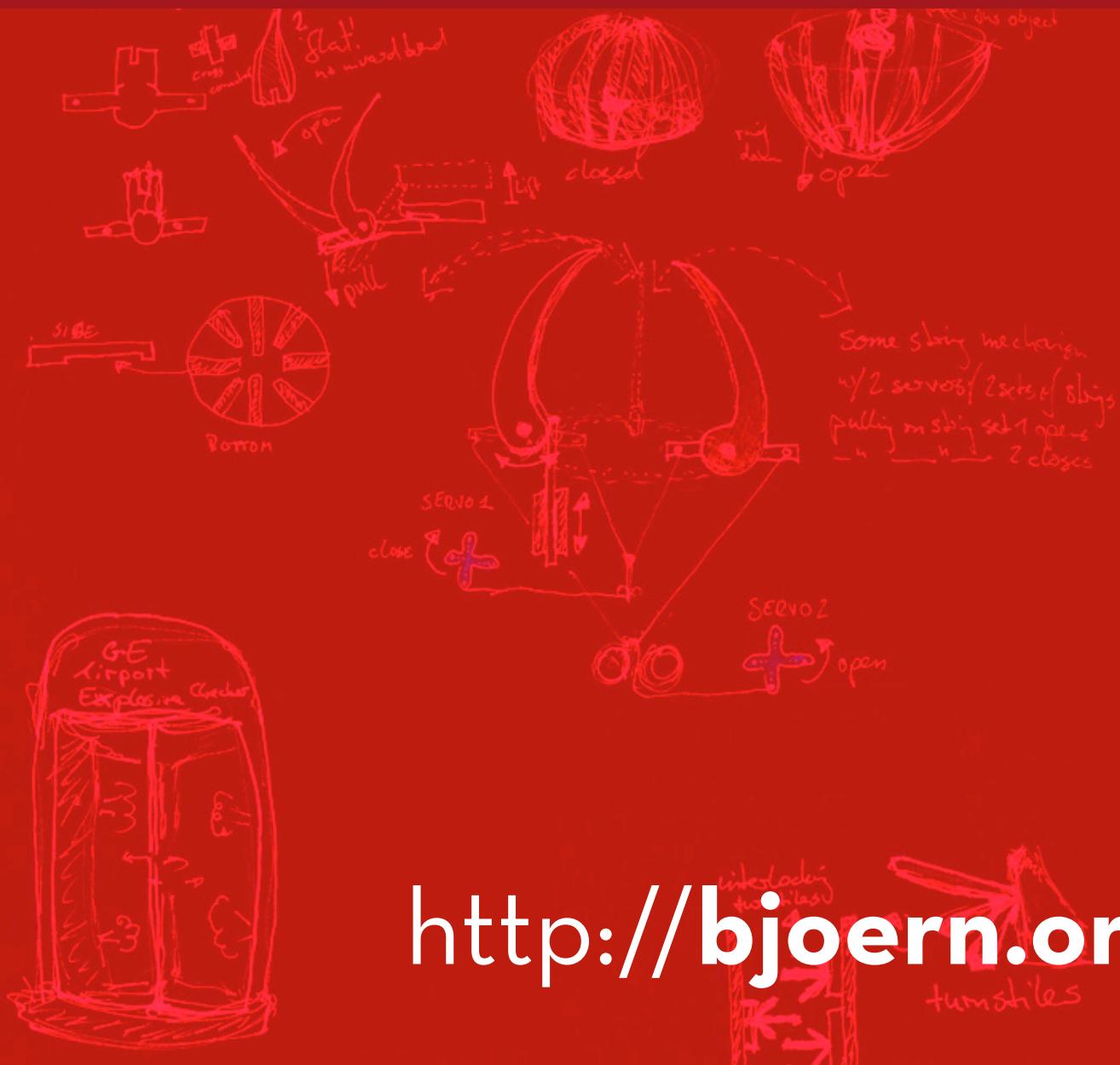
FTIR Mouse



Applies the principle of Frustrated Total Internal Reflection to illuminate a user's fingers, and uses a camera to track multiple points of touch on its curved translucent surface.

Mouse 2.0: Multi-touch Meets the Mouse

Nicolas Villar, Shahram Izadi, Dan Rosenfeld, Hrvoje Benko, John Helmes, Jonathan Westhues, Steve Hodges, Eyal Ofek, Alex Butler, Xiang Cao and Billy Chen. Proceedings of UIST 2009.



<http://bjoern.org>

attach the wires to
the middle tube

Bill: copyright
visualization of license



Scott: a gate that shows
who walked through it last

Bill: a gate that measures
ceremonial gates