

STANFORD / CS448B



Graph and Tree Layout

Jeffrey Heer

ASSISTANT: Jason Chuang

4 February 2009

<http://cs448b.stanford.edu>

Assignment 3: Visualization Software

Create an interactive visualization application. Choose a data domain and select an appropriate visualization technique.

1. Choose a data set and storyboard your interface
2. Implement the interface using tools of your choice
3. Submit your application and produce a final write-up

You may work individually or in groups of 2.

Due by *end of day* on **Wednesday, February 11**



Final Project

Design a new visualization technique or system

- Implementation of new design or system
- 8-12 page in conference paper format
- 2 Project Presentations

Schedule

- Project Proposal: **Wednesday, February 18** (*end of day*)
- Initial Presentation: **Monday, February 23 & Wednesday, February 25**
- Poster Presentation: **Monday, March 16** (Time TBD)

Logistics

- Groups of up to 3 people, graded individually
- Clearly report responsibilities of each member

Topics

Graph and Tree Visualization

- Tree Layout
- Graph Layout

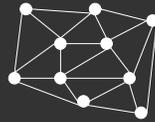
Goals

- Overview of layout approaches and their strengths and weaknesses
- Insight into implementation techniques

Graphs and Trees

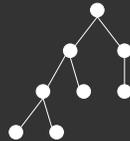
Graphs

- Model relations among data
- *Nodes and edges*



Trees

- Graphs with hierarchical structure
 - Connected graph with $N-1$ edges
- Nodes as *parents* and *children*



Spatial Layout

The primary concern of graph drawing is the spatial layout of nodes and edges

Often (but not always) the goal is to effectively depict the graph structure

- Connectivity, path-following
- Network distance
- Clustering
- Ordering (e.g., hierarchy level)

Applications of Tree / Graph Layout

Tournaments
Organization Charts
Genealogy
Diagramming (e.g., Visio)
Biological Interactions (Genes, Proteins)
Computer Networks
Social Networks
Simulation and Modeling
Integrated Circuit Design

Tree Visualization

Indentation

- Linear list, indentation encodes depth

Node-Link diagrams

- Nodes connected by lines/curves

Enclosure diagrams

- Represent hierarchy by enclosure

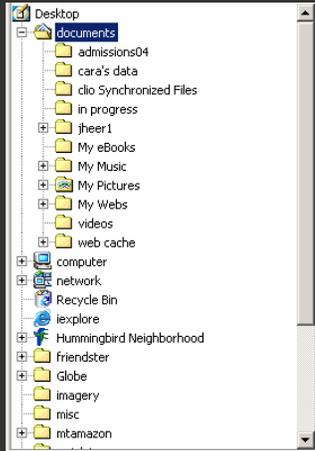
Layering

- Layering and alignment



Tree layout is fast: $O(n)$ or $O(n \log n)$, enabling real-time layout for interaction.

Indentation



Places all items along vertically spaced rows

Indentation used to show parent/child relationships

Commonly used as a component in an interface

Breadth and depth contend for space

Often requires a great deal of scrolling



Node-Link Diagrams

Nodes are distributed in space, connected by straight or curved lines

Typical approach is to use 2D space to break apart breadth and depth

Often space is used to communicate hierarchical orientation (typically towards authority or generality)

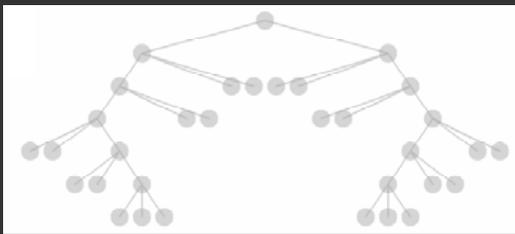


Basic Recursive Approach

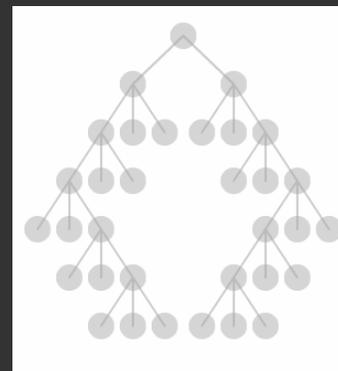
Repeatedly divide space for subtrees by leaf count

- Breadth of tree along one dimension
- Depth along the other dimension

Problem: exponential growth of breadth



Reingold & Tilford's Tidier Layout



Goal: make smarter use of space, maximize density and symmetry.

Originally for binary trees, extended by Walker to cover general case.

This extension was corrected by Buchheim et al to achieve a linear time algorithm.

Problems with Node-Link Diagrams

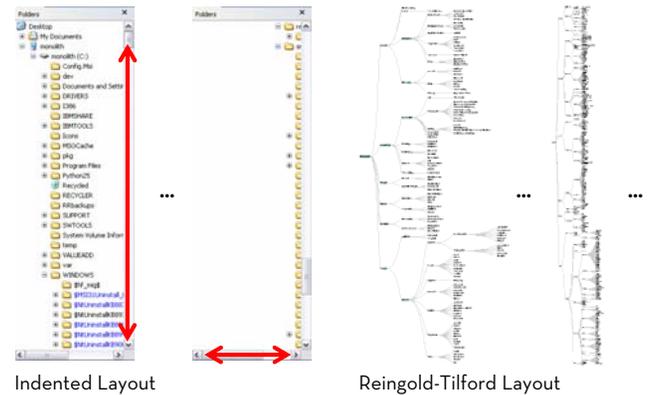
Scale

- Tree breadth often grows exponentially
- Even with tidier layout, quickly run out of space

Possible solutions

- Filtering
- Focus+Context
- Scrolling or Panning
- Zooming
- Aggregation

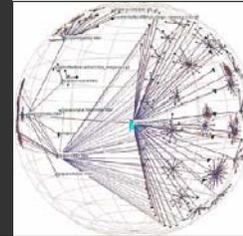
Visualizing Large Hierarchies



Hyperbolic Layout



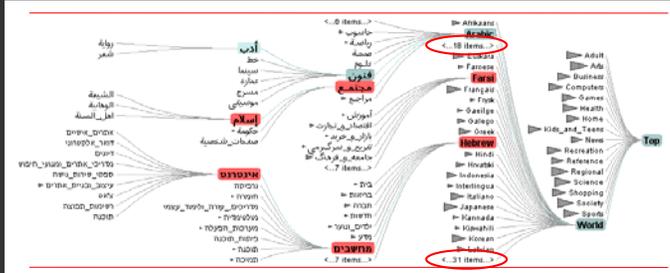
Perform tree layout in hyperbolic geometry, then project the result on to the Euclidean plane.



Why? Like tree breadth, the hyperbolic plane expands exponentially!

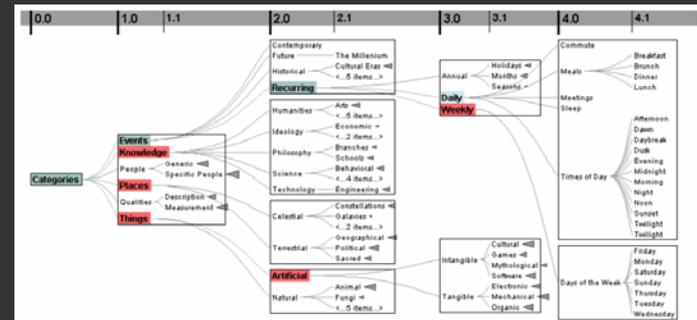
Also computable in 3D, projected into a sphere.

Degree-of-Interest Trees [AVI 04]



Space-constrained, multi-focal tree layout

Degree-of-Interest Trees



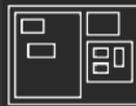
Cull “un-interesting” nodes on a per block basis until all blocks on a level fit within bounds.

Attempt to center child blocks beneath parents.

Enclosure Diagrams

Encode structure using spatial enclosure

Popularly known as TreeMaps



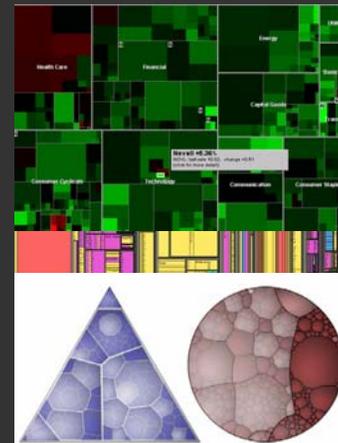
Benefits

- Provides a single view of an entire tree
- Easier to spot large/small nodes

Problems

- Difficult to accurately read depth

TreeMaps



Recursively fill space based on a size metric for nodes. Enclosure signifies hierarchy.

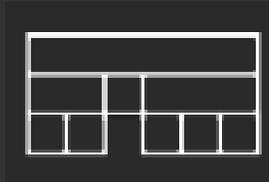
Additional measures can be taken to control aspect ratio of cells.

Often uses rectangles, but other shapes are possible, e.g., iterative Voronoi tessellation.

Layered Diagrams

Signify tree structure using

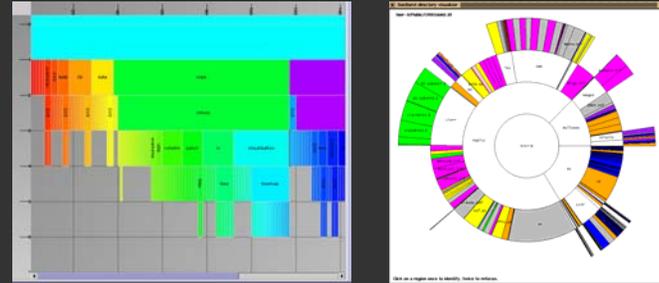
- Layering
- Adjacency
- Alignment



Involves recursive sub-division of space

We can apply the same set of approaches as in node-link layout.

Icicle and Sunburst Trees



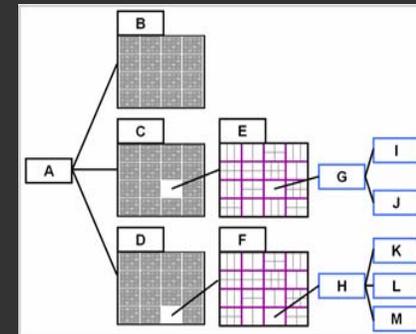
Higher-level nodes get a larger layer area, whether that is horizontal or angular extent.

Child levels are layered, constrained to parent's extent

Layered Tree Drawing

		Coffee			Espresso		
		Amaretto	Columbian	Decaf Irish Cr..	Caffe Latte	Caffe Mocha	Decaf Espresso
Central	Colorado						
	Illinois						
	Iowa						
	Missouri						
	Ohio						
East	Wisconsin						
	Connecticut						
	Florida						
	Massachusetts						
	New Hamps..						
South	New York						
	Louisiana						
	New Mexico						
West	Oklahoma						
	Texas						
	California						
	Nevada						
	Oregon						
Utah							
Washington							

Hybrids are also possible...



“Elastic Hierarchies”
Node-link diagram
with treemap nodes.

Graph Visualization

Approaches to Graph Drawing

Direct Calculation using Graph Structure

- Tree layout on spanning tree
- Hierarchical layout
- Adjacency matrix layout

Optimization-based Layout

- Constraint satisfaction
- Force-directed layout

Attribute-Driven Layout

- Layout using data attributes, not linkage

Spanning Tree Layout

Many graphs are tree-like or have useful spanning trees

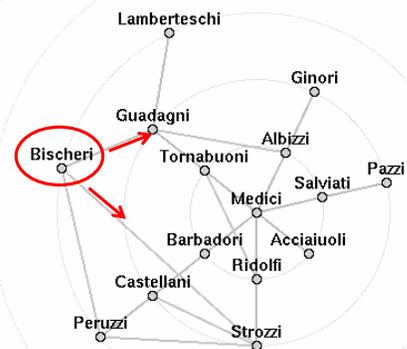
- Websites, Social Networks

Use tree layout on spanning tree of graph

- Trees created by BFS / DFS
- Min/max spanning trees

Fast tree layouts allow graph layouts to be recalculated at interactive rates

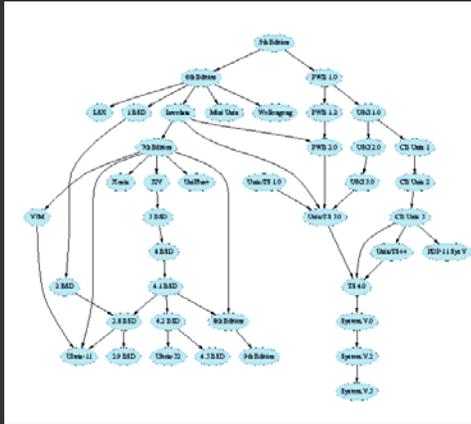
Heuristics may further improve layout



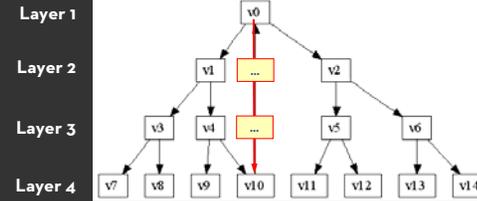
Spanning tree layout may result in arbitrary parent node

Sugiyama-style graph layout

Evolution of the UNIX operating system
Hierarchical layering based on descent



Sugiyama-style graph layout



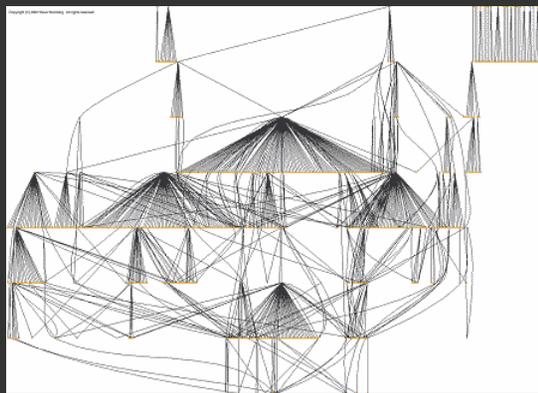
Assign nodes to hierarchy layers

- Reverse edges to remove cycles
- Create dummy nodes to "fill in" missing layers

Arrange nodes within layer, minimize edge crossings

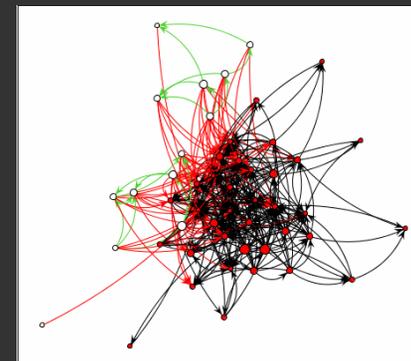
Route edges - layout splines if needed

Hierarchical graph layout



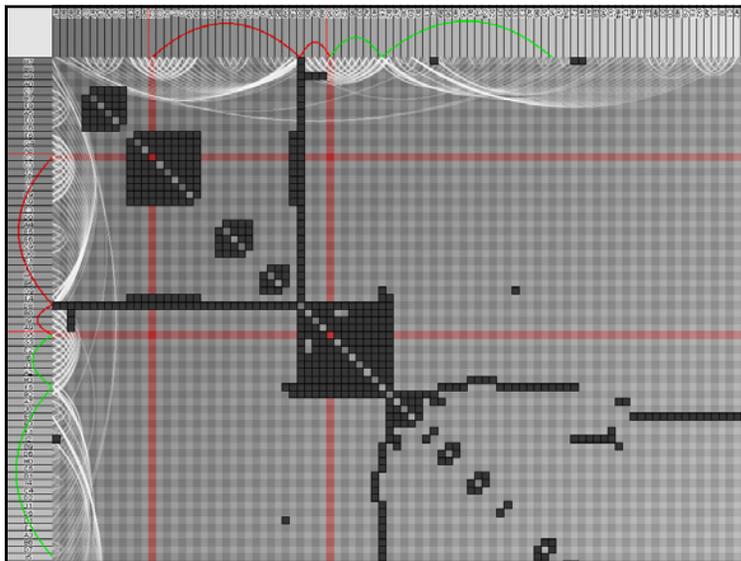
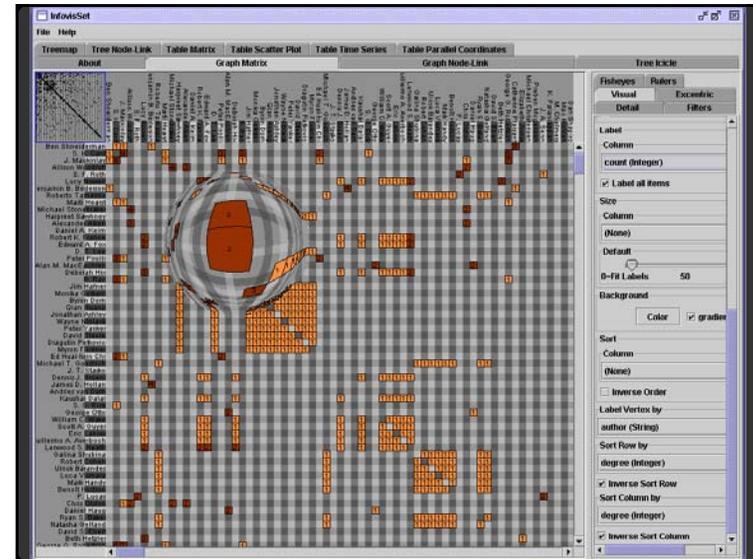
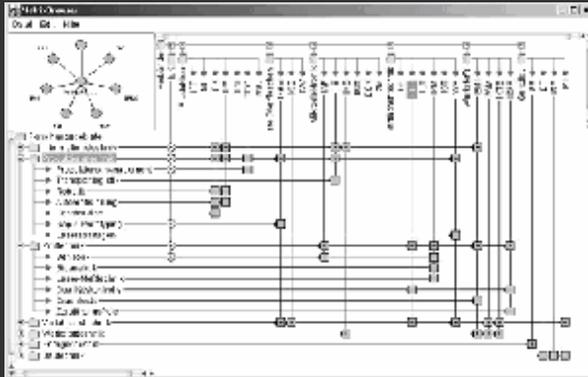
Gnutella network

Limitations of Node-Link Layout



Edge-crossings and occlusion

Adjacency Matrices



Optimization Techniques

Treat layout as an *optimization problem*

- Define layout using a set of *constraints*: equations the layout should try to obey
- Use optimization algorithms to solve

Common approach for undirected graphs

- *Force-Directed Layout* most common

We can introduce directional constraints

- *DiG-CoLa* (Di-Graph Constrained Optimization Layout) [Dwyer 05]

Optimizing “Aesthetic” Constraints

Minimize edge crossings

Minimize area

Minimize line bends

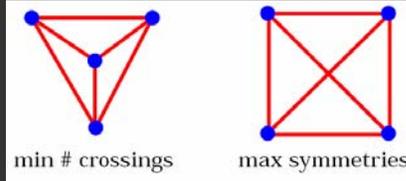
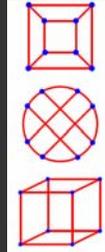
Minimize line slopes

Maximize smallest angle between edges

Maximize symmetry

but, can't do it all.

Optimizing these criteria is often NP-Hard, requiring approximations.



Force-Directed Layout

Edges = springs

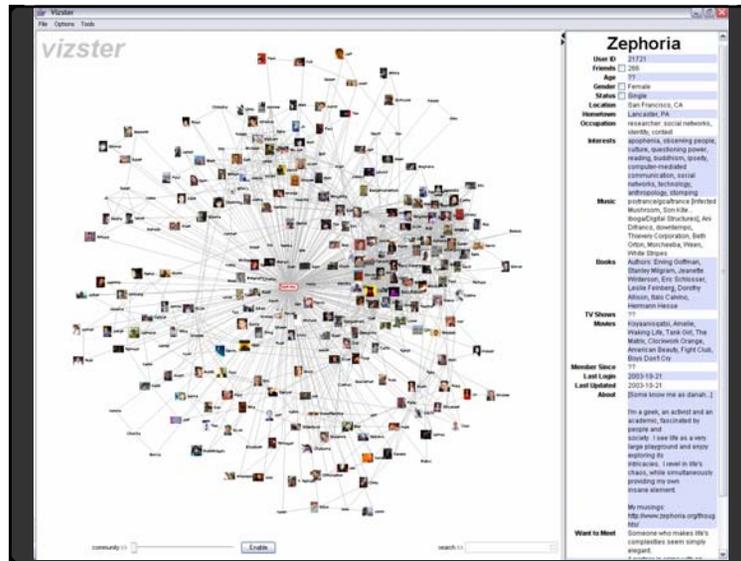
$$F = -k * (x - L)$$

Nodes = charged particles

$$F = G * m_1 * m_2 / x^2$$

Repeatedly calculate forces, update node positions

- Naïve approach $O(N^2)$, speed up to $O(N \log N)$ quadtree
- Numerical integration of forces at each time step



Constrained Optimization Layout

Minimize stress function

$$\text{stress}(X) = \sum_{i < j} w_{ij} (\|X_i - X_j\| - d_{ij})^2$$

- X : node positions, d : optimal edge length,
- w : normalization constants
- Use global (*majorization*) or localized (*gradient descent*) optimization

→ Says: Try to place nodes d_{ij} apart

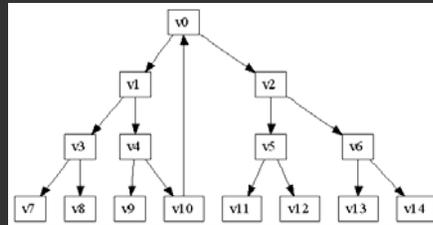
Add hierarchy ordering constraints

$$E_H(y) = \sum_{(i,j) \in E} (y_i - y_j - \delta_{ij})^2$$

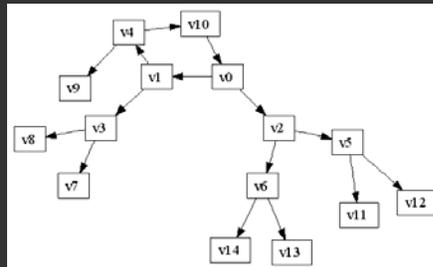
- y : node y -coordinates
- δ : edge direction (e.g., 1 for $i \rightarrow j$, 0 for undirected)

→ Says: If i points to j , it should have a lower y -value

Sugiyama layout (dot)
Preserve tree structure

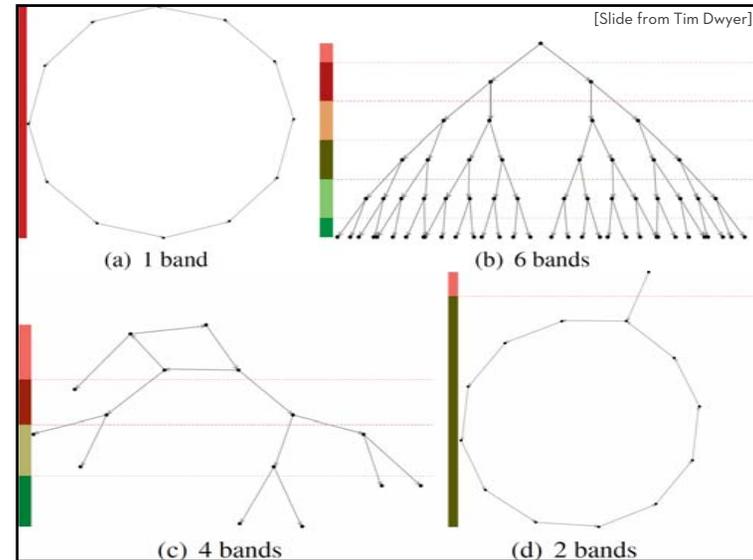


DiG-CoLa method
Preserve edge lengths



[Slide from Tim Dwyer]

[Slide from Tim Dwyer]



Attribute-Driven Layout

Large node-link diagrams get messy!
Is there additional structure we can exploit?

Idea: Use data attributes to perform layout
• e.g., scatter plot based on node values

Dynamic queries and/or brushing can be used to explore connectivity

Attribute-Driven Layout

The “Skitter” Layout

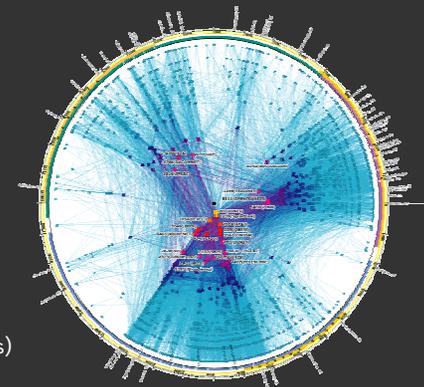
- Internet Connectivity
- Radial Scatterplot

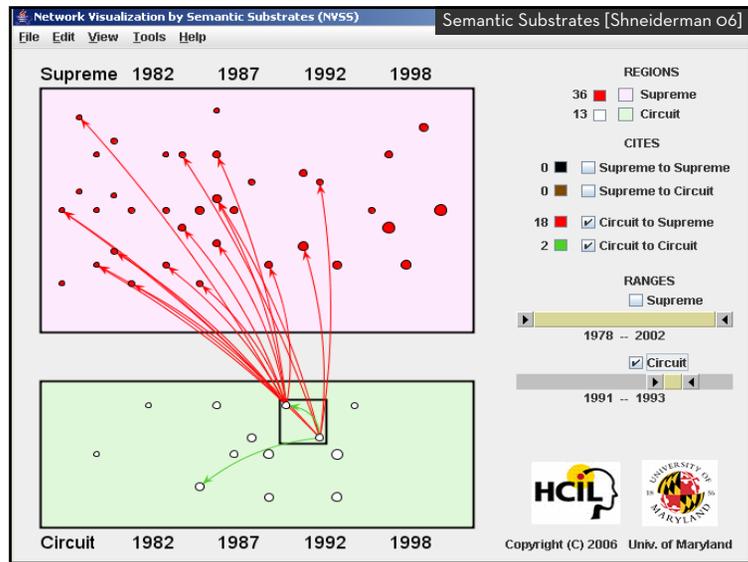
Angle = Longitude

- Geography

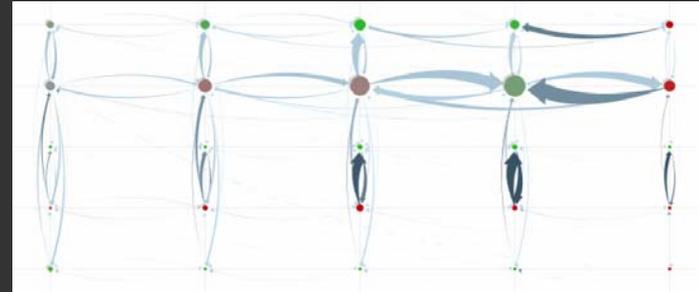
Radius = Degree

- # of connections
- (a statistic of the nodes)



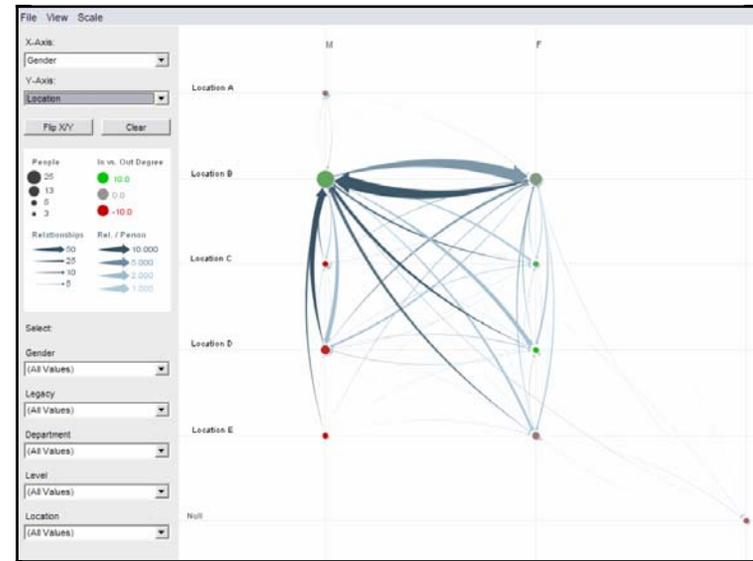
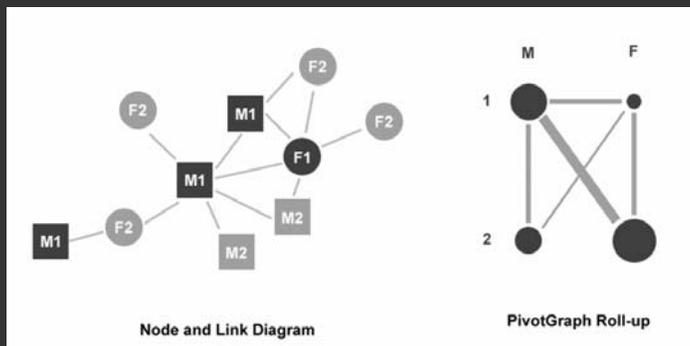


PivotGraph [Wattenberg 2006]

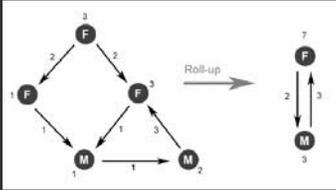


Layout aggregated graphs according to node attributes.
Analogous to pivot tables and trellis display.

PivotGraph

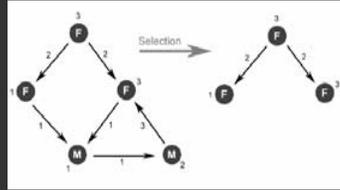


Operators



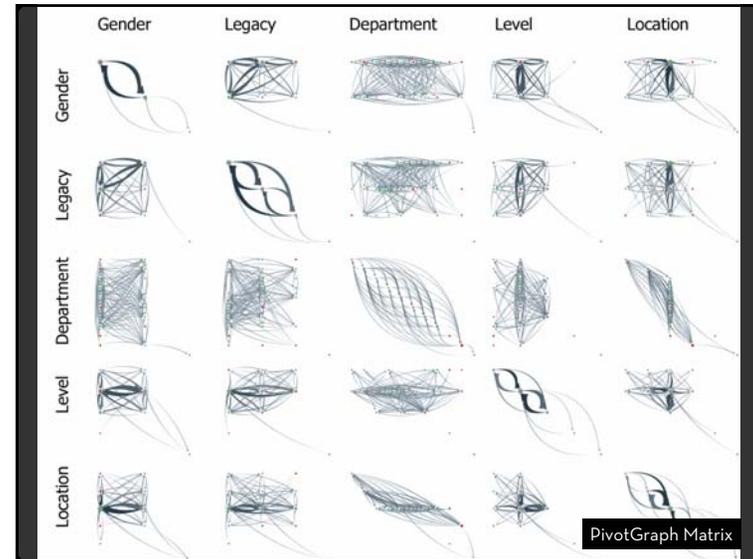
Roll-Up

Aggregate items with matching data values



Selection

Filter on data values



Limitations of PivotGraph

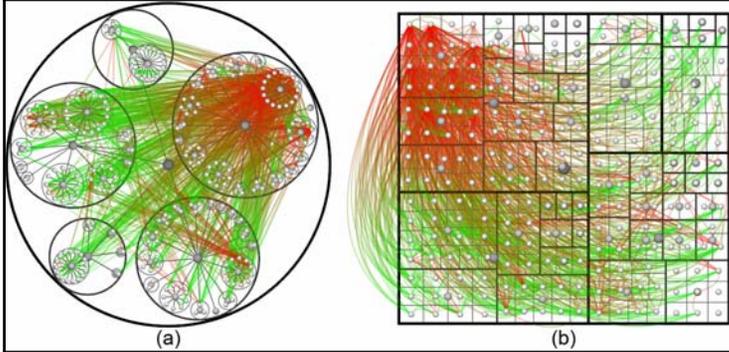
Only 2 variables (no nesting as in Tableau)

Doesn't support continuous variables

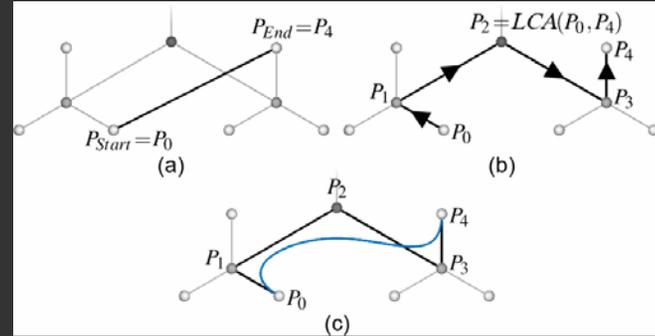
Multivariate edges?

Hierarchical Edge Bundles

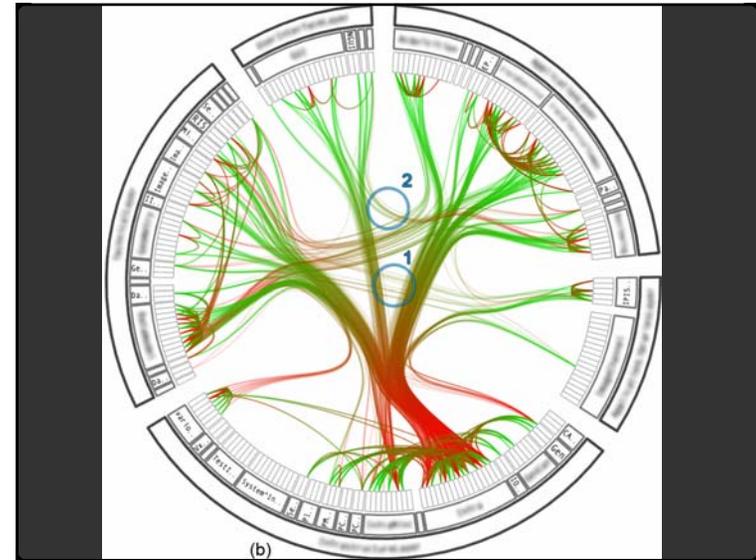
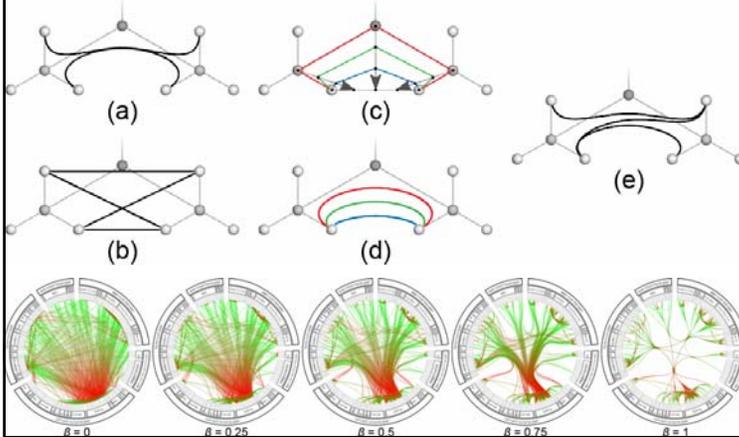
Trees with Adjacency Relations



Bundle Edges along Hierarchy



Configuring Edge Tension



Summary



Tree Layout

- Indented / Node-Link / Enclosure / Layers
- How to address issues of scale?
 - Filtering and Focus + Context techniques

Graph Layout

- Tree layout over spanning tree
- Hierarchical “Sugiyama” Layout
- Optimization Techniques
- Attribute-Driven Layout